

AN0008

Application Note

Jump to Boot Memory

Introduction

There is a boot memory in the memory map of AT32F4xx, which stores the bootloader. To execute the bootloader, the user must configure it through BOOT pin, generally pulling up BOOT0 and pulling down BOOT1. In actual application, the BOOT pin may not be connected, and it is not possible to enter bootloader by switching BOOT pin. Therefore, this application note is written to introduce how to directly jump from user code to bootloader.

Note: The corresponding code in this application note is developed on the basis of V2.x.x BSP provided by Artery. For other versions of BSP, please pay attention to the differences in usage.

Applicable products:

Part number	AT32Fxx
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1 Software implementation

1.1 Preconditions for jumping to bootloader

Before jumping from user code to boot memory to execute the bootloader, the user must complete the following operations:

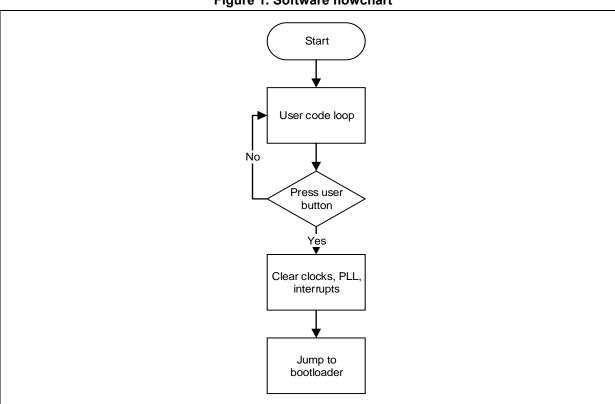
- 1) Disable all peripheral clocks;
- 2) Disable PLL;
- 3) Disable all interrupts;
- 4) Clear all pending interrupt flags.

Jumping to bootloader can be implemented by the following two methods:

- Method 1: Use code to complete the aforementioned four steps, and then jump to bootloader directly (the corresponding clocks, PLL and interrupts are cleared according to the peripherals enabled by customer's code).
- 2) Method 2: Automatically clear by performing a reset. After reset, jump to bootloader before initialization of user code in SystemInit.

1.2 Implementation method 1

Use the AT-START evaluation board to design a user program "APPJumpToBootloaderMethod1", which is mainly used to complete a LED operation. Then, detect a user button; when the button is pressed, jump to the bootloader directly (interrupts need to be cleared before jumping). If it is complex to clear all clocks and interrupts before jumping, the user can select method 2 to clear by performing a reset.







1.2.1 Method 1 code implementation

The main function is mainly a LED and a detection button. Press the button if you need to enter the bootloader.

```
int main(void)
{
     uint32 t LedTimer = 0, LedTog = 0;
     system clock config();
     at32 board init();
     LedTog = system core clock/80;
     while(1)
     {
          if(USER BUTTON == at32 button press())
          {
               /*Clear Clock, PLL, Interrupt*/
               app_clear_sys_status ();
               app jump to bootloader ();
          }
          if(LedTimer == LedTog)
          {
               at32_led_toggle(LED4);
               LedTimer = 0;
          }
          LedTimer ++;
     }
}
```

The app_jump_to_bootloader function is used for jumping to the bootloader.

```
void app_jump_to_bootloader(void)
{
    uint32_t dwStkPtr, dwJumpAddr;
    dwStkPtr = *(uint32_t *)BOOTLOADER_ADDRESS;
    dwJumpAddr = *(uint32_t *)(BOOTLOADER_ADDRESS + sizeof(uint32_t));
    /* Before jumping to the bootloader, make sure that all peripheral clocks, PLL and
interrupts are disabled, and all interrupt pending bits are cleared. */
    SET_MSP(dwStkPtr);
    pfTarget = (void (*)(void))dwJumpAddr;
    pfTarget();
}
```



The app_clear_sys_status function is used to disable clocks, PLL, interrupts and clear pending interrupt flags.

```
void app_clear_sys_status()
{
     /*Close Peripherals Clock*/
     CRM->apb2rst = 0xFFFF;
     CRM->apb2rst = 0;
     CRM->apb1rst = 0xFFFF;
     CRM->apb1rst = 0;
     CRM->apb1en = 0;
     CRM->apb2en = 0;
     /*Close PLL*/
     /* Reset SW, AHBDIV, APB1DIV, APB2DIV, ADCDIV and CLKOUT_SEL bits */
     CRM->cfg_bit.sclksel = 0;
     CRM->cfg_bit.ahbdiv = 0;
     CRM->cfg bit.apb1div = 0;
     CRM->cfg bit.apb2div = 0;
     CRM->cfg_bit.adcdiv_l = 0;
     CRM->cfg bit.adcdiv h = 0;
     CRM->cfg_bit.clkout_sel = 0;
     CRM->ctrl_bit.hexten = 0;
     CRM->ctrl bit.cfden = 0;
     CRM->ctrl bit.pllen = 0;
     CRM->cfg_bit.pllrcs = 0;
     CRM->cfg_bit.pllhextdiv = 0;
     CRM->cfg bit.pllmult I = 0;
     CRM->cfg_bit.pllmult_h = 0;
     CRM->cfg bit.usbdiv I = 0;
     CRM->cfg bit.usbdiv h = 0;
     CRM->cfg_bit.pllrange = 0;
     /* Disable all interrupts and clear pending bits */
     CRM->clkint_bit.lickstblfc = 0;
     CRM->clkint bit.lextstblfc = 0;
     CRM->clkint_bit.hickstblfc = 0;
     CRM->clkint bit.hextstblfc = 0;
     CRM->clkint_bit.pllstblfc = 0;
     CRM->clkint bit.cfdfc = 0;
     /*Close Systick*/
     SysTick->CTRL = 0;
     /*Disable ALL interrupt && Pending Interrupt Flag*/
     /*Clear interrupts and pending interrupt flags according to peripherals enabled by users*/
     /*
     user add code ...
     */
}
```



Implementation method 2 1.3

Method 2 performs a reset to jump to the bootloader before initialization of user code in SystemInit.

We use the AT-START evaluation board to design a user program "APPJumpToBootloaderMethod2", which mainly completes a LED operation. Then, detect a user button; when the button is pressed, jump from the user program to the bootloader. At this point, write 0x5AA5 to the BPR_DATA1 register, and then generate a software reset. After software reset, judge whether the 0x5AA5 is written to BPR DATA1 at the beginning of SystemInit; then, clear the BPR DATA1. If BPR DATA1=0x5AA5, jump to the bootloader (jump at the beginning of SystemInit, so as to prevent the user code from not matching the bootloader settings after initialization).

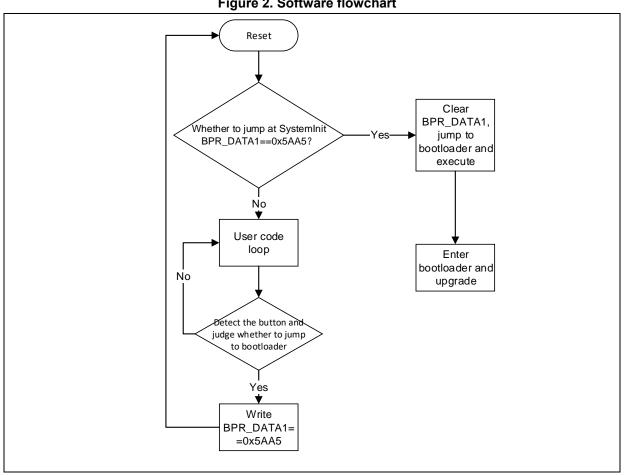


Figure 2. Software flowchart

1.3.1 Method 2 code implementation

The main function is mainly a LED and a detection button. Press the button if you need to enter the bootloader.

```
int main(void)
{
     uint32_t LedTimer = 0, LedTog = 0;
     system clock config();
     at32 board init();
     LedTog = system_core_clock/80;
     while(1)
     {
          if(USER BUTTON == at32 button press())
          {
               /* Save a BPR status flag, indicating that APP needs to jump to bootloader */
               BPR Write Flag();
          }
          if (LedTimer == LedTog)
          {
               at32 led toggle(LED4);;
               LedTimer = 0;
          }
          LedTimer ++;
     }
}
```

The *bpr_write_flag* function is mainly used to write a jump flag to BPR_DATA1 and perform software reset.

```
void bpr_write_flag (void)
{
    /* enable pwc and bpr clock */
    crm_periph_clock_enable(CRM_PWC_PERIPH_CLOCK, TRUE);
    crm_periph_clock_enable(CRM_BPR_PERIPH_CLOCK, TRUE);
    /* enable write access to bpr domain */
    pwc_battery_powered_domain_access(TRUE);
    /* clear tamper pin event pending flag */
    bpr_flag_clear(BPR_TAMPER_EVENT_FLAG);
    bpr_data_write(BPR_DATA1, BKP_JUMP_FLAG);
    pwc_battery_powered_domain_access(FALSE);
    /*System Reset*/
    NVIC_SystemReset();
}
```



The *bpr_check_flag* function is mainly used to judge whether to jump to the bootloader after reset. Return 1: jump to bootloader; return 0: not to jump.

```
uint8 t bpr check flag (void)
{
    uint8 t ret val = 0;
    /* enable pwc and bpr clock */
    crm periph clock enable(CRM PWC PERIPH CLOCK, TRUE);
    crm periph clock enable(CRM BPR PERIPH CLOCK, TRUE);
    /* enable write access to bpr domain */
    pwc_battery_powered_domain_access(TRUE);
    /* clear tamper pin event pending flag */
    bpr flag clear(BPR TAMPER EVENT FLAG);
    if(bpr_data_read(BPR_DATA1) == BPR_JUMP_FLAG)
    {
         bpr_data_write(BPR_DATA1, 0x00); //write 00 to bkp
         ret val = 1;
    }
    pwc battery powered domain access(FALSE);
    crm_periph_clock_enable(CRM_PWC_PERIPH_CLOCK, FALSE);
    crm periph clock enable(CRM BPR PERIPH CLOCK, FALSE);
    return ret_val;
}
```

The *app_jump_to_bootloader* is used for jumping to the bootloader.

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```
void app_jump_to_bootloader (void)
{
    uint32_t dwStkPtr, dwJumpAddr;
    dwStkPtr = *(uint32_t *)BOOTLOADER_ADDRESS;
    dwJumpAddr = *(uint32_t *)(BOOTLOADER_ADDRESS + sizeof(uint32_t));
    /* Before jumping to the bootloader, make sure that all peripheral clocks, PLL and
interrupts are disabled, and all interrupt pending bits are cleared. */
    SET_MSP(dwStkPtr);
    pfTarget = (void (*)(void))dwJumpAddr;
    pfTarget();
}
```

Before initialization of user code in SystemInit, judge whether to jump to the bootloader.

```
void SystemInit (void)
{
#if defined (___FPU_USED) && (___FPU_USED == 1U)
  SCB->CPACR |= ((3U << 10U * 2U) |
                                        /* set cp10 full access */
                  (3U << 11U * 2U) ); /* set cp11 full access */
#endif
    /*check if need to go into bootloader*/
    if(bpr_check_flag () == 1)
     {
         app_jump_to_bootloader ();
    }
  /* reset the crm clock configuration to the default reset state(for debug purpose) */
  /* set hicken bit */
  CRM->ctrl_bit.hicken = TRUE;...
}
```



2 Test of jumping to bootloader through user code

The AT-STAT-F403AV1.0 evaluation board is used for the test, and upgrade by the means of DFU (serial port upgrade process is the same).

- 1. Download APPJumpToBootloaderMethod1 or APPJumpToBootloaderMethod2 to the AT-START-F403A V1.0 evaluation board;
- 2. LED3 blinks;
- 3. Press PB2 USER button, and the LED3 will be OFF, indicating entering bootloader successfully;
- 4. Plug and unplug the USB on the AT-STAT-F403A V1.0 board;
- 5. Open Artery ISP Programmer, and you can find that an USB DFU device is connected.

👞 Artery ISP Pr	ogrammer_V1.5.47		_	×
;		RY 雅华	专力	
		e, then click next to open	n connection	
Port Type	USB DFU 🗸			1
Nums	VID 2E3C	PID DF11	UID AT32	
<			>	

Figure 3. ISP Programmer device connection

6. Upgrade the program according to ISP upgrade process.

Figure 4. ISP Progra	ammer upgrade proces	S
Artery ISP Programmer_V1.5.47	- 🗆 X	
#12[<u></u>2]	雅特力	
Target: AT32F403AVGT7_1024K		
Operation: Download File Name: D:\LED.bin File Sire: 100824B	Status: 100824B	
Erase Running Download —— (LED bin) Running Operation finished successfully!		
Time: 00:00:03	100%	



3 Revision history

Table 1. Document	revision	history
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Date	Version	Revision note
2021.12.8	2.0.0	Initial release



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