

## Segger J-Scope on AT32 MCU

## Introduction

This application note introduces how to use J-Scope on AT32 MCUs.

In actual applications, it is relatively complex to use serial host or MDK logic analyzer to display data in the form of waveform. Instead, Segger J-Scope is more easy-to-use, with hardware to be connected to J-Link only.

*Note: The corresponding code in this application note is developed on the basis of V2.x.x BSP provided by Artery. For other versions of BSP, please pay attention to the differences in usage.*

Applicable products:

Part number	AT32Fxx family
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# 1 Segger J-Scope

## 1.1 Introduction

J-Scope is a free-of-charge software to analyze and visualize data on a microcontroller in real-time, while the target is running.

Sampling can be done using either SEGGER High-Speed-Sampling (HSS) or SEGGER RTT technology.

- 1) In HSS mode: Use J-Scope to directly load executable files of MDK or IAR, which is easy but has a low sampling rate.
- 2) In RTT mode: Add Segger RTT component to the user program, which is more complex but more practical with a higher sampling rate.

## 1.2 Software/hardware version

Hardware-JLINK: JLINK BASE V9 and above are required; JLINK PRO/JLINK ULTRA V4 and above are required.

Software-MDK: MDK4 or MDK5. This application note uses MDK5.

## 1.3 Applicable devices

- 1) J-Scope supports the below devices in HSS mode.

**Figure 1. Applicable devices in HSS mode**

Core	HSS
ARM7, ARM9, ARM11	✗
Cortex-M0	✓
Cortex-M1	✓
Cortex-M3	✓
Cortex-M4	✓
Cortex-M7	✓
Cortex-A, Cortex-R	✗
RX100	✓
RX200	✓
RX600	✓
PIC32	✗

- 2) J-Scope supports the below devices in RTT mode.

**Figure 2. Applicable devices in RTT mode**

Core	RTT
Cortex-M0	✓
Cortex-M0+	✓
Cortex-M1	✓
Cortex-M3	✓
Cortex-M4	✓
Cortex-M7	✓
RX100	✓
RX200	✓
RX600	✓

## 1.4 J-Link sampling rate

Data in Figure 3 below is applicable to HSS mode, while RTT mode does not have such limitations. Basically, the sampling rate in RTT mode can be high enough as long as it supported by J-Link.

For JLINK BASE, the data for “other models” is applicable, which means that HSS mode supports 10 variables, with the maximum sampling rate of 1 KHz.

Figure 3. J-Link sampling rate

J-Link Model	Max. no. of variables	Max. sampling frequency
J-Link PRO (V4 or later)	100	Unlimited <sup>1</sup>
J-Link ULTRA- (V4 or later)	100	Unlimited <sup>1</sup>
Other models	10	1 kHz <sup>2</sup>

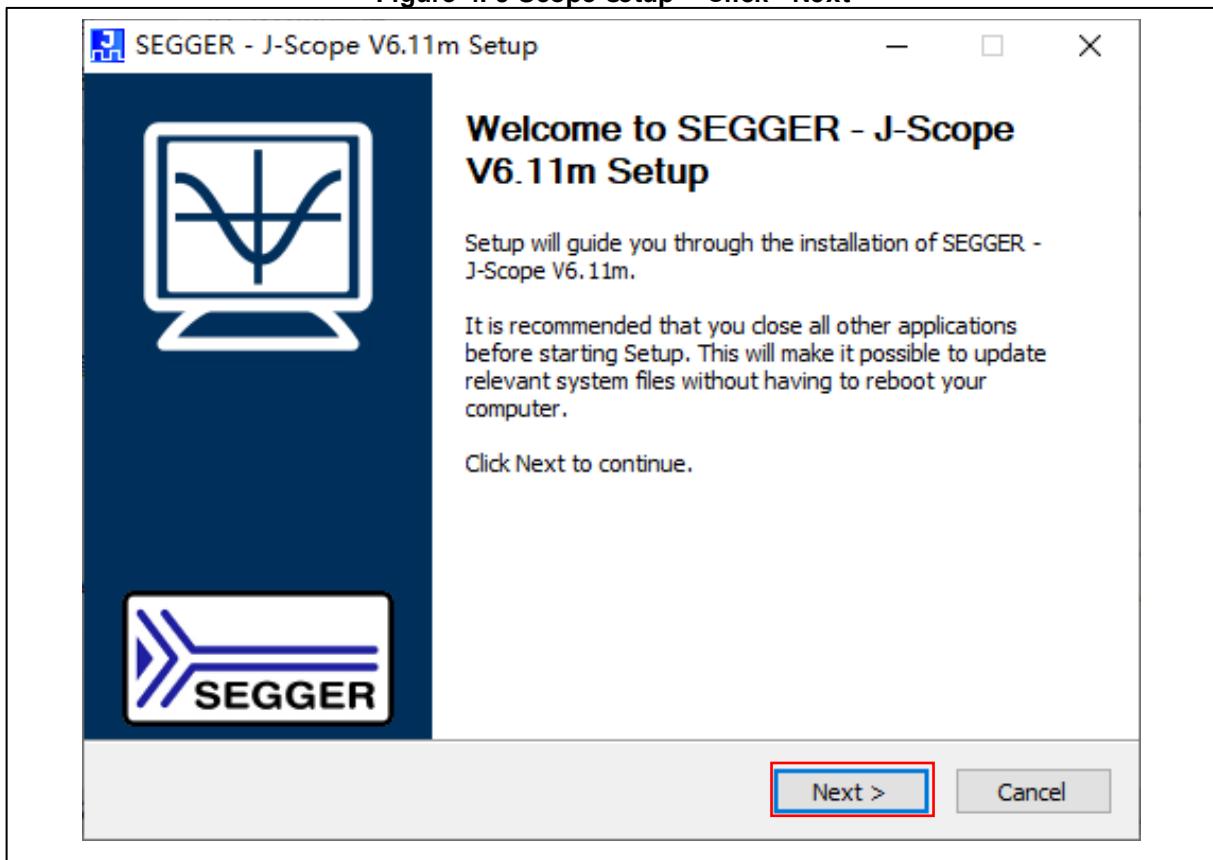
## 2 J-Scope preparation

This section uses MDK5 and AT32F403A for demonstration.

### 2.1 J-Scope setup

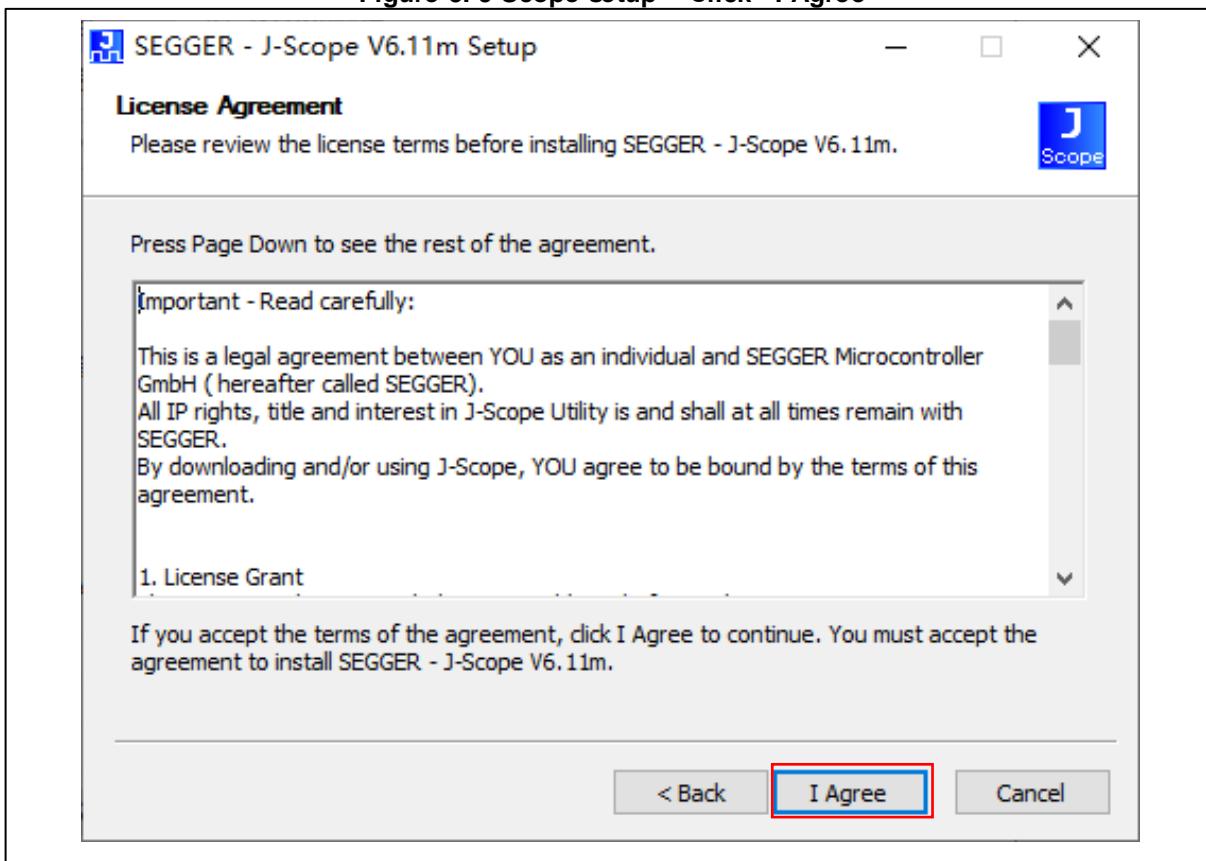
- 1) Unzip xx\AN0044\_Segger\_Jscope\_on\_AT32\_MCU \JScopeTool\Setup\_JScope\_V6xxm.zip;
- 2) Double click Setup\_JScope\_V6xxm.exe to start setup;
- 3) Click "NEXT";

Figure 4. J-Scope setup – Click “Next”



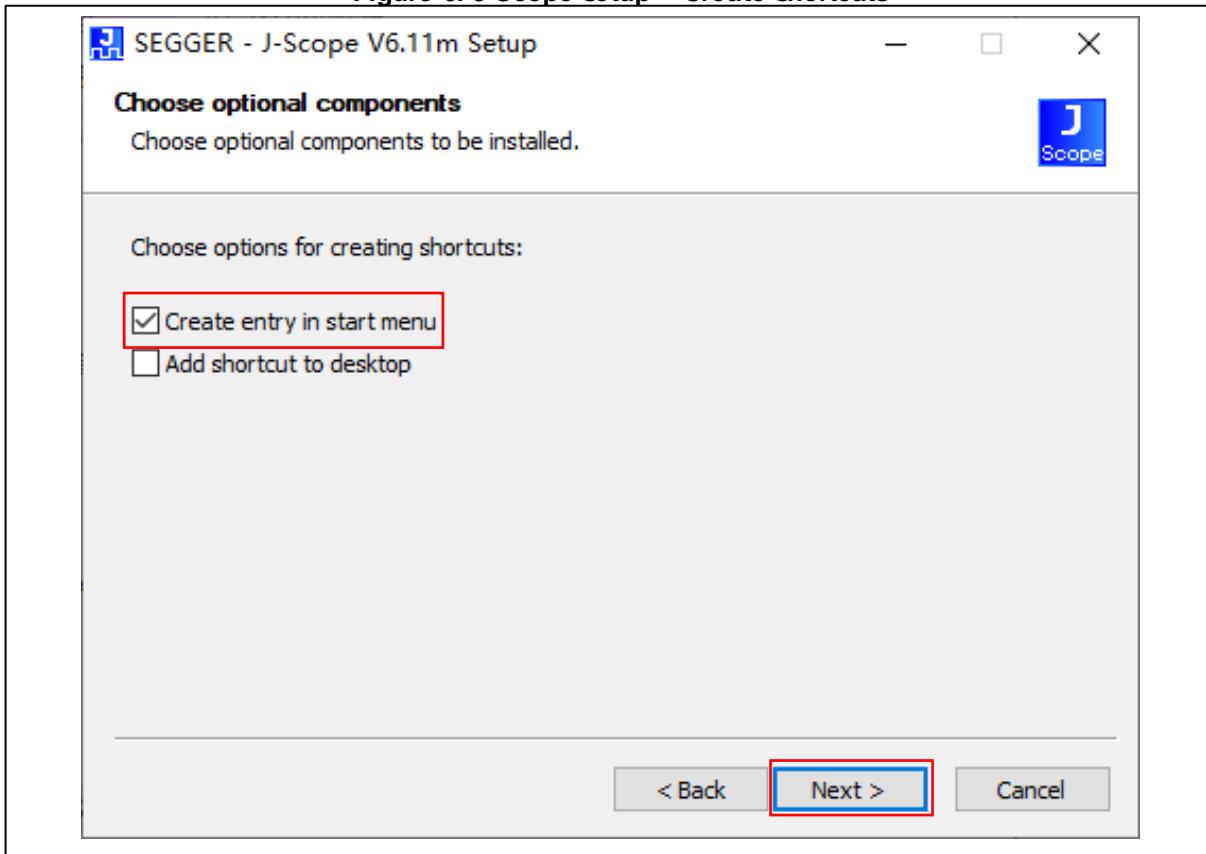
- 4) Click "I Agree";

Figure 5. J-Scope setup – Click "I Agree"



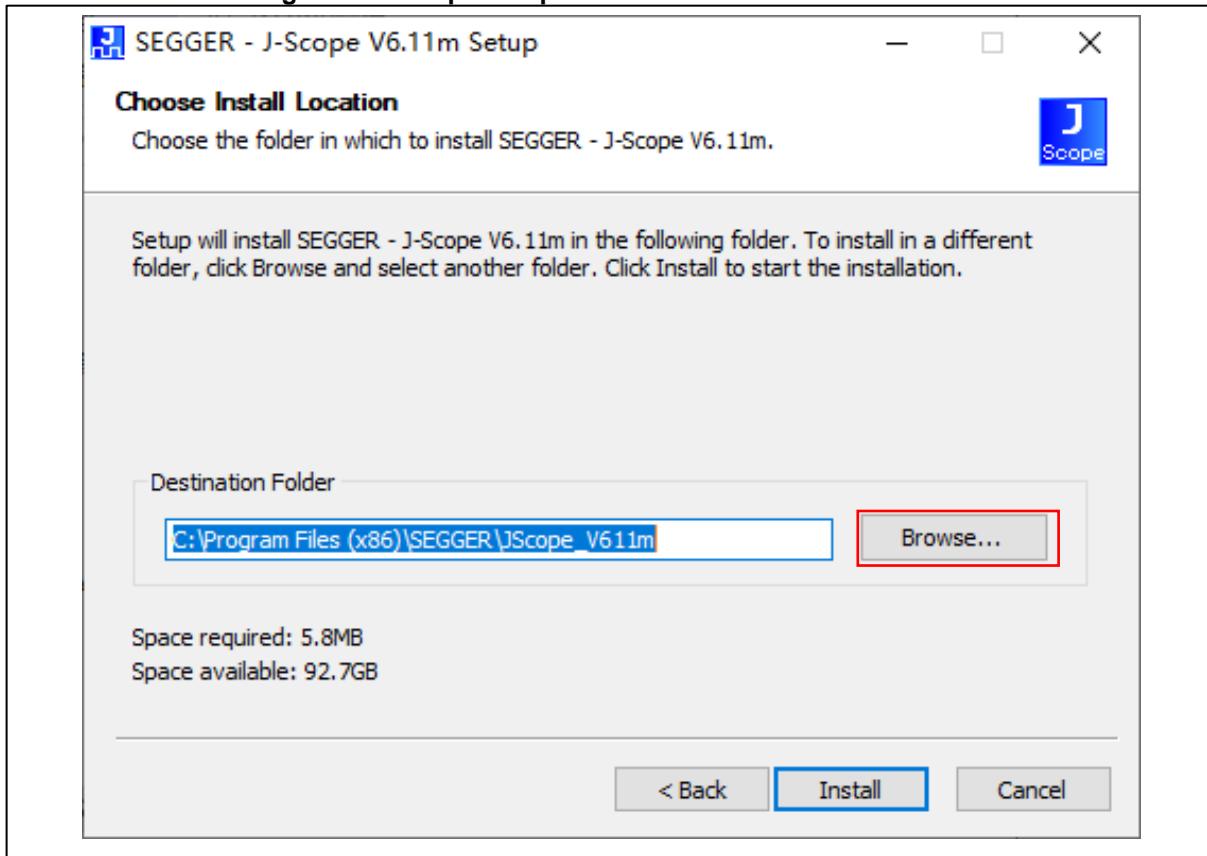
- 5) Tick "Create entry in start menu" and then click "NEXT";

Figure 6. J-Scope setup – Create shortcuts



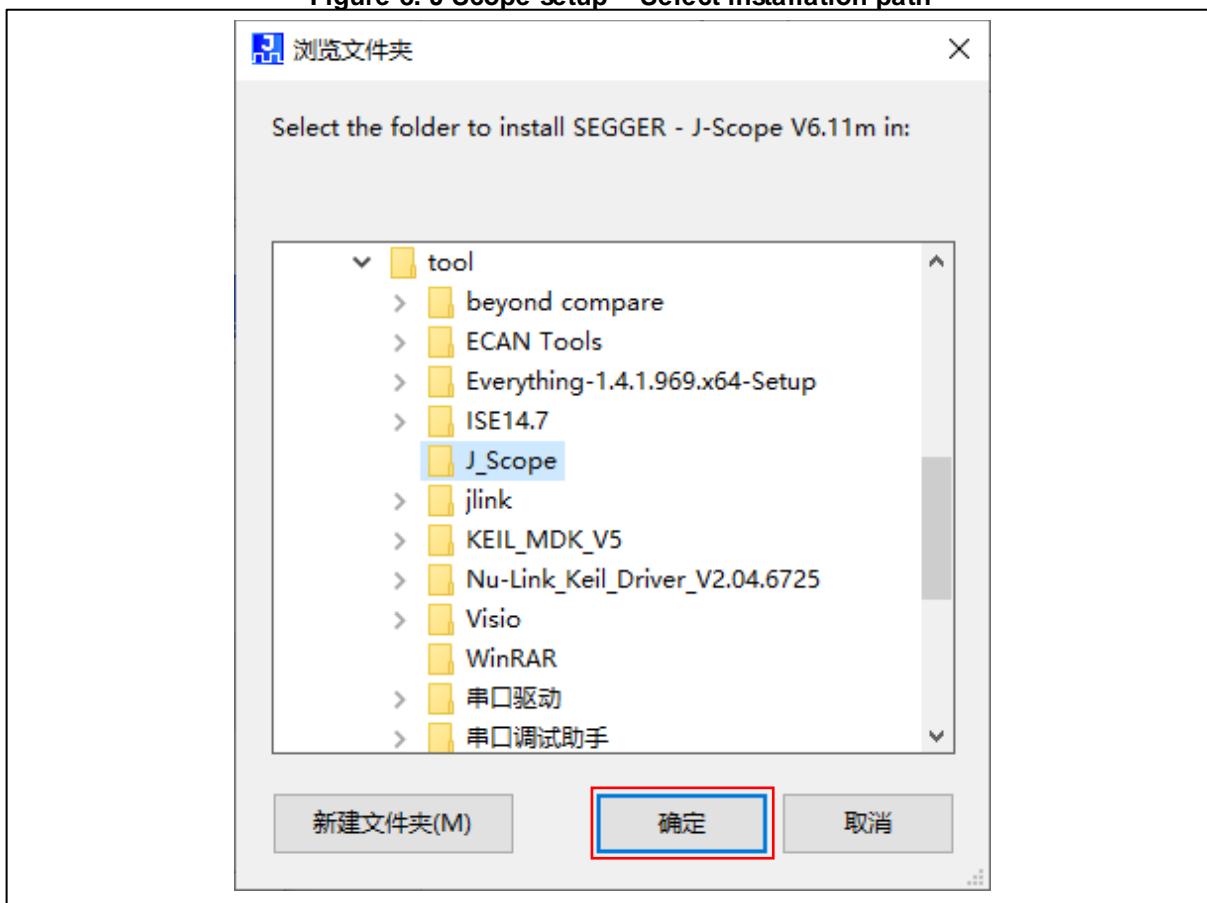
- 6) Click "Browse" and select the destination folder;

Figure 7. J-Scope setup – Browse and Destination Folder



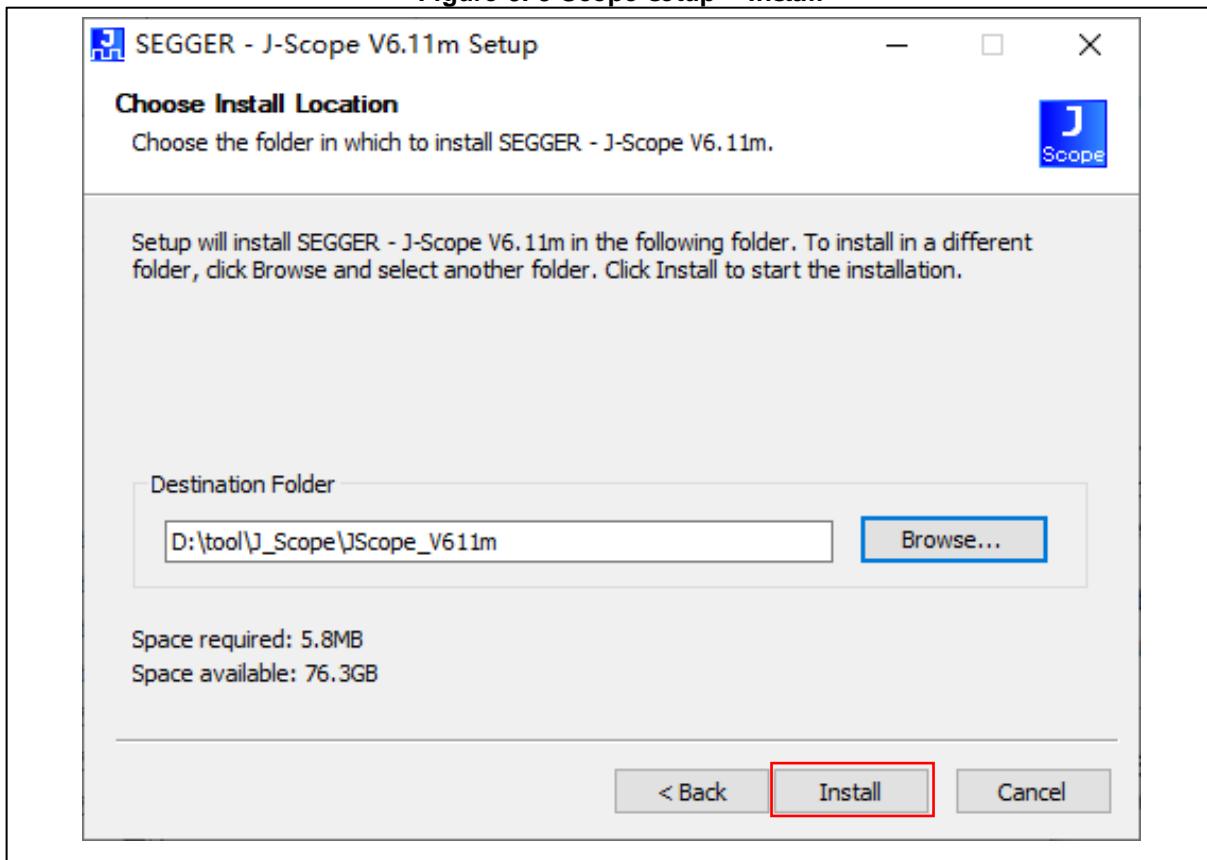
- 7) Select the installation path and click “OK”. Users can choose the desired installation path. In this example, it is “D:\tool\J\_Scope”.

Figure 8. J-Scope setup – Select installation path



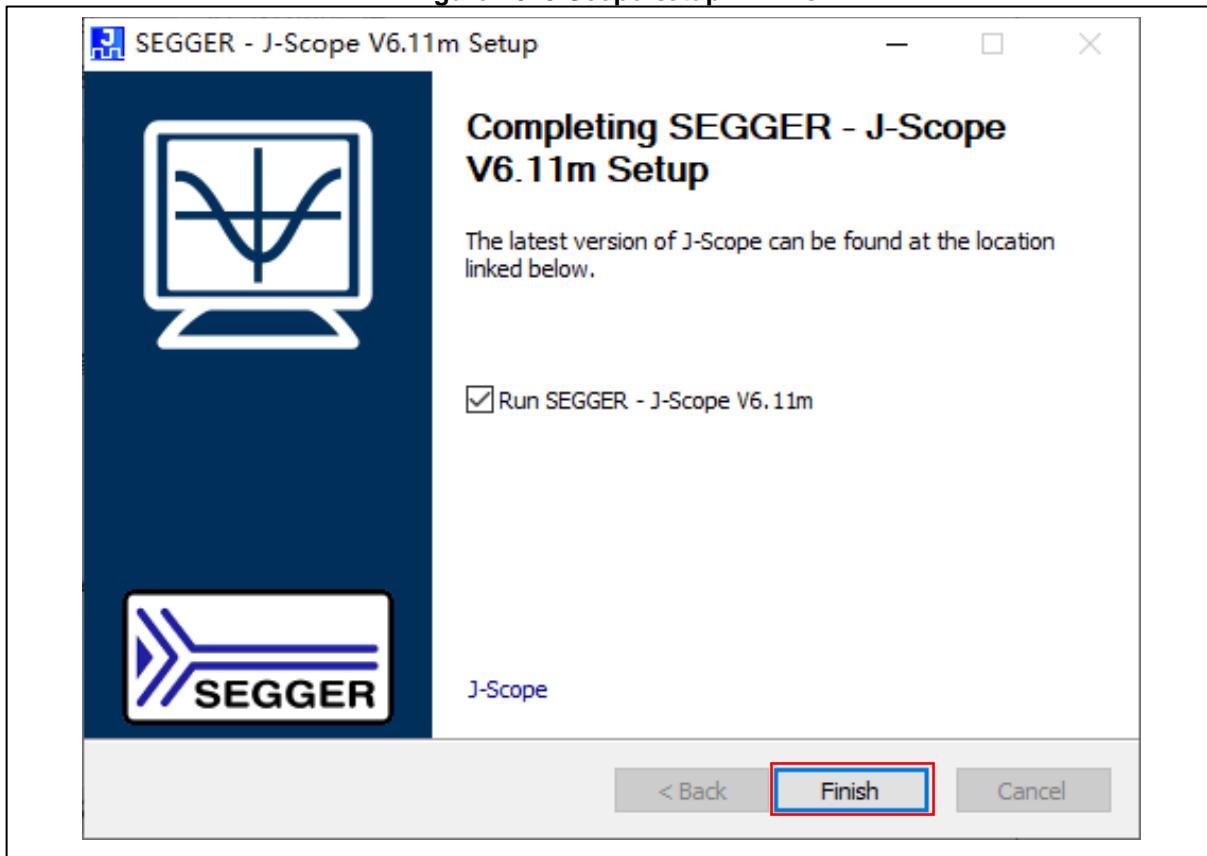
- 8) Click “Install”;

Figure 9. J-Scope setup – Install



9) Click "Finish" to complete setup.

Figure 10. J-Scope setup – Finish



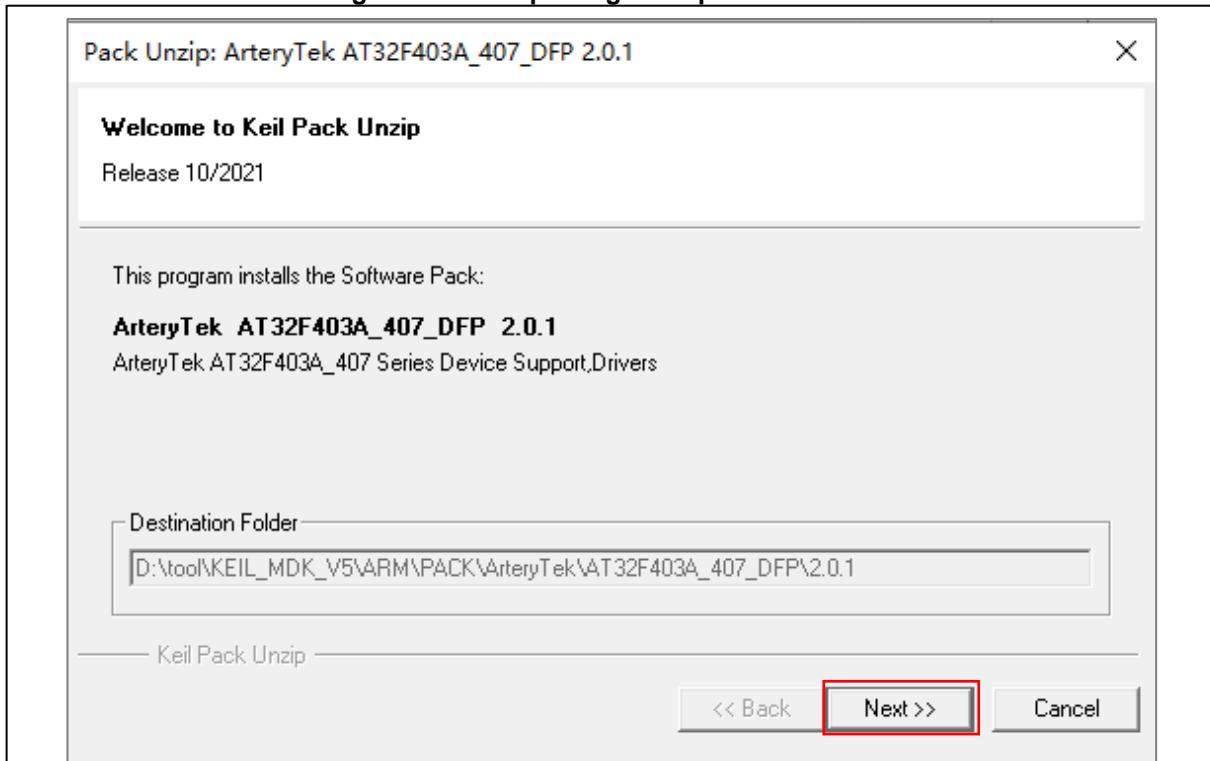
## 2.2 Install AT32 related package

- 1) Unzip xx\AN0044\_Segger\_Jscope\_on\_AT32\_MCU\_2.x.x\JScopeTool\PACKs\_V2.x.x.zip;
- 2) Unzip Keil5\_AT32MCU\_AddOn.zip;
- 3) Install ArteryTek.AT32F403A\_407\_DFP.2.x.x.pack and Segger\_AT32MCU\_AddOn.exe.

### 2.2.1 ArteryTek.AT32F403A\_407\_DFP.2.x.x.pack

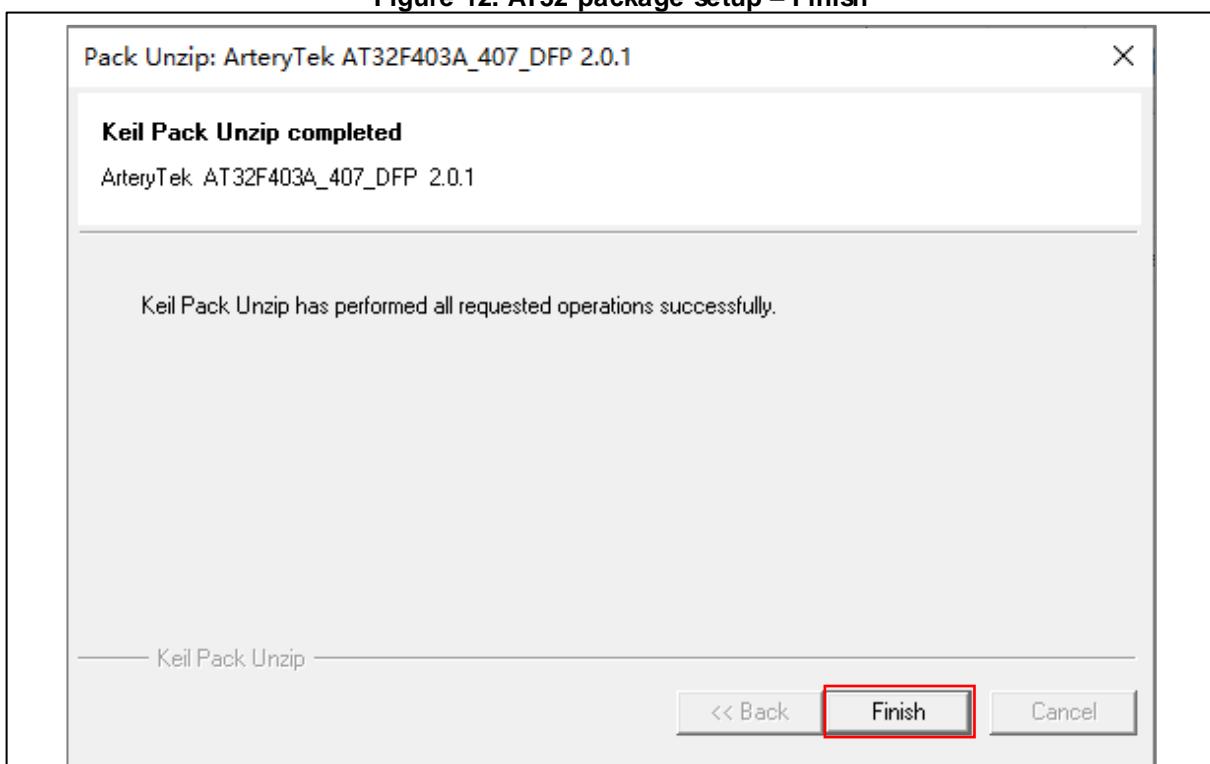
- 1) Double click *ArteryTek.AT32F403A\_407\_DFP.2.x.x.pack*;
- 2) Click "NEXT";

Figure 11. AT32 package setup – Click “NEXT”



- 3) Click "Finish" to complete installation

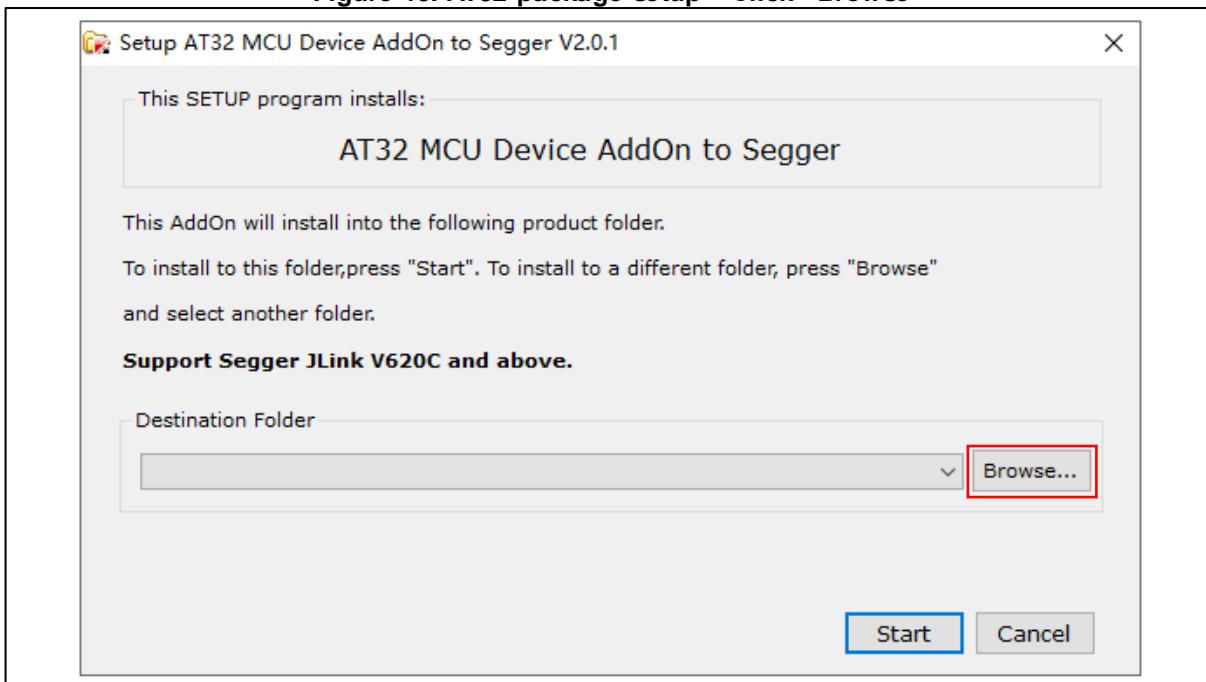
Figure 12. AT32 package setup – Finish



## 2.2.2 Segger\_AT32MCU\_AddOn.exe

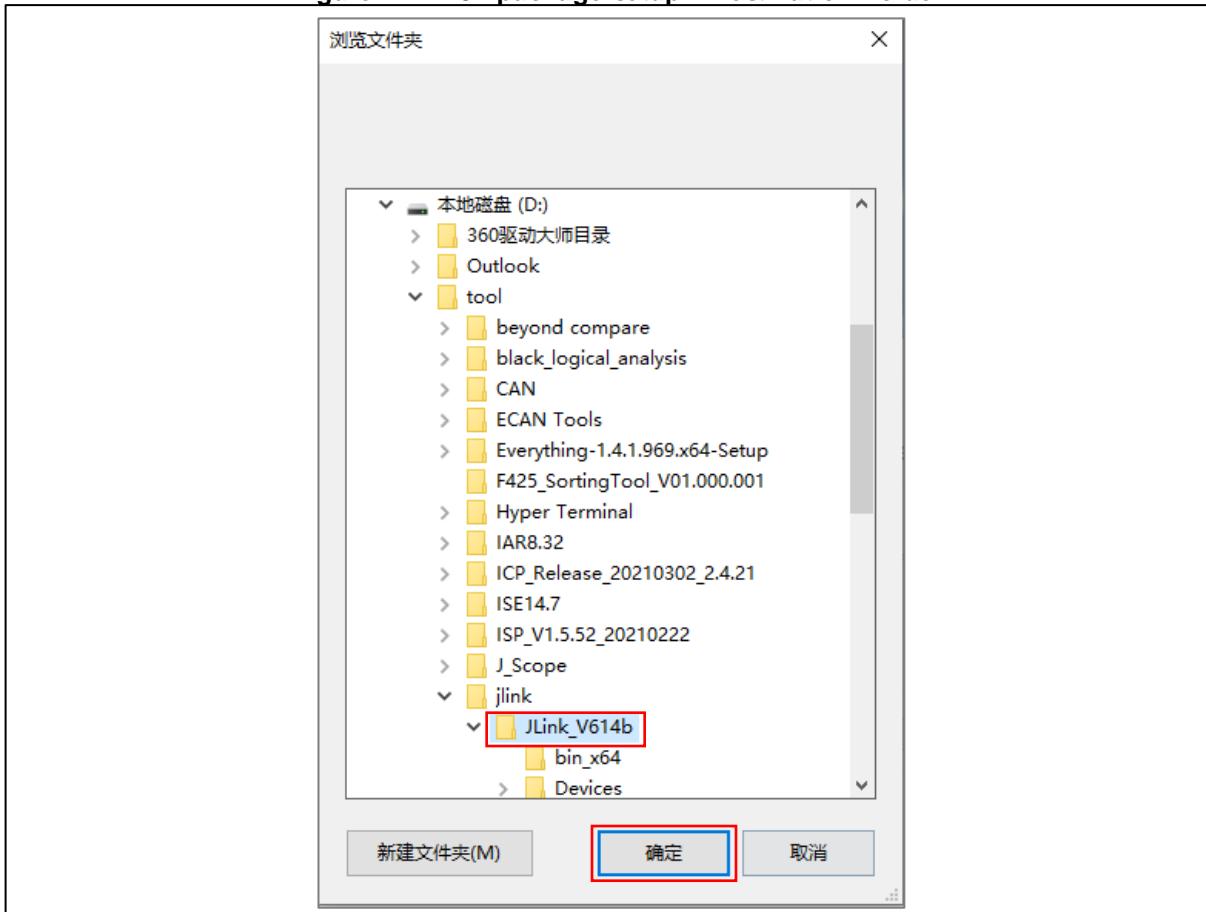
- 1) Double click Segger\_AT32MCU\_AddOn.exe;
- 2) Click "Browse" and select the destination folder;

Figure 13. AT32 package setup – Click “Browse”

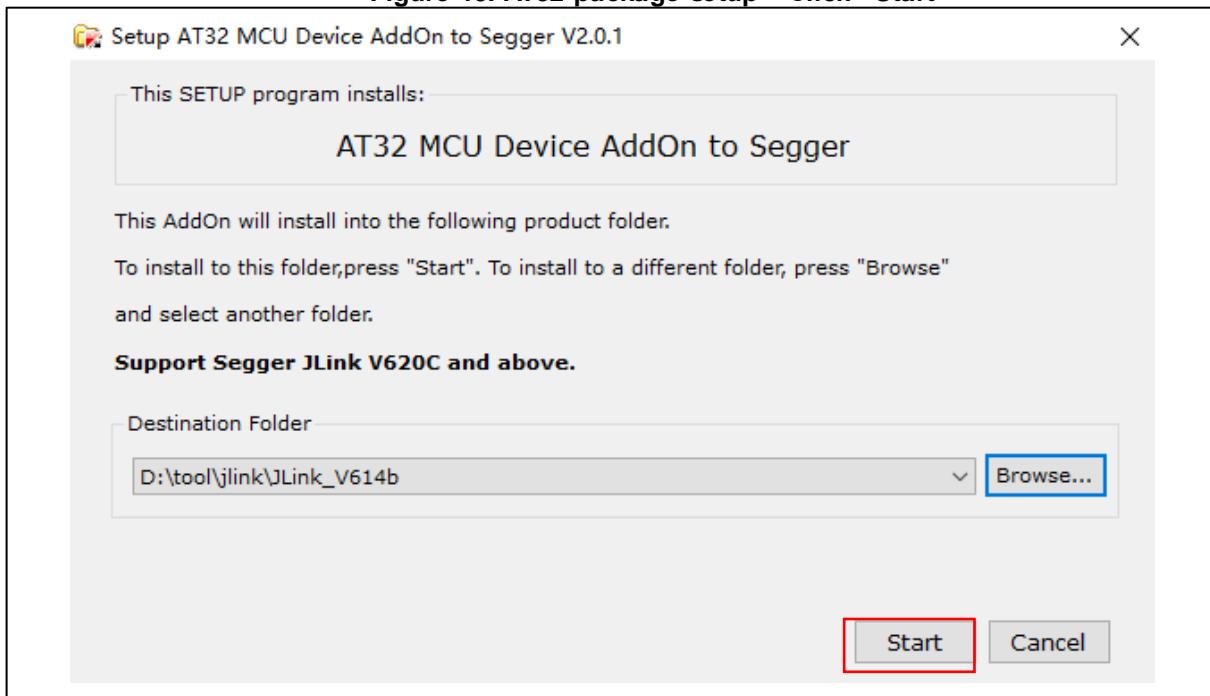


- 3) Select the installation path. Select the J-Link installation path; otherwise, the *JLinkDevices.xml* cannot be found.

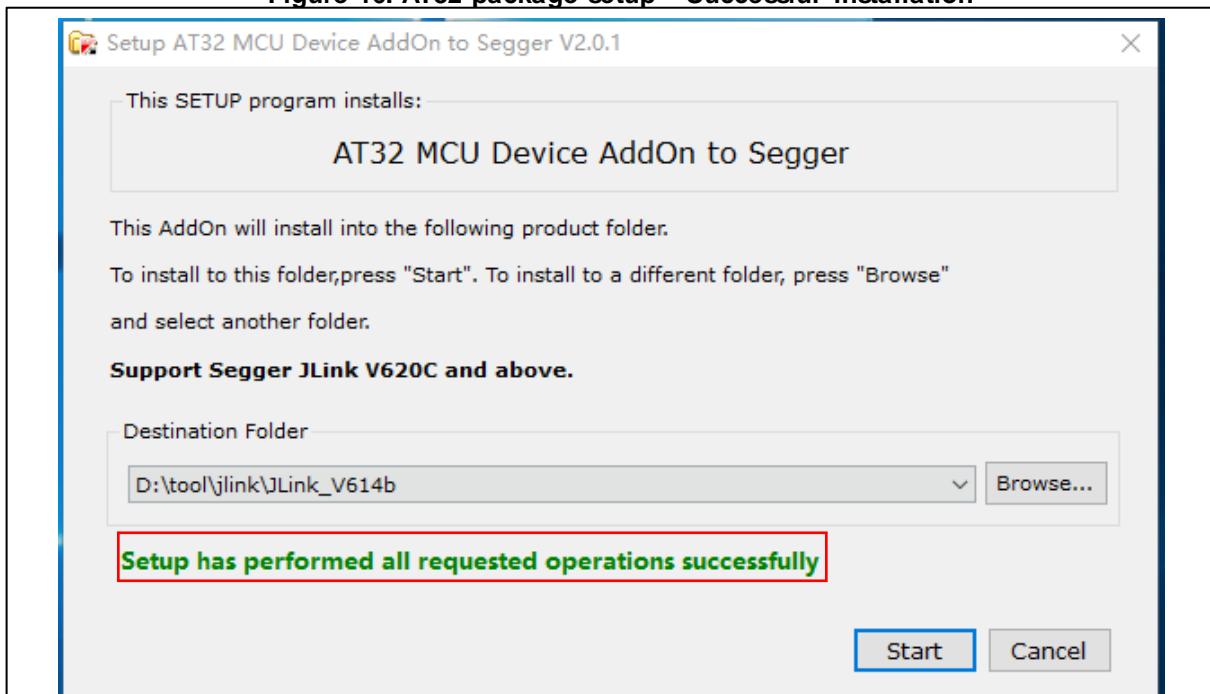
Figure 14. AT32 package setup – Destination Folder



- 4) Click "Start" to start setup;

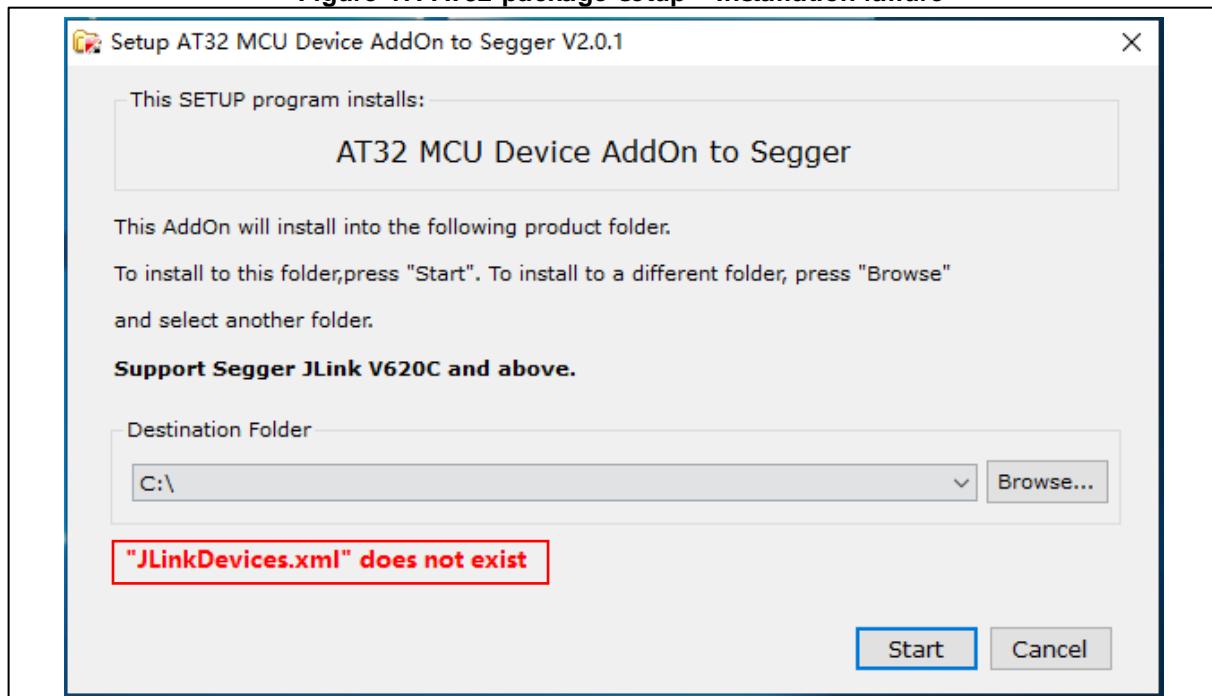
**Figure 15. AT32 package setup – Click “Start”**

- 5) If AT32 package is installed successfully, a message in green font will display.

**Figure 16. AT32 package setup – Successful installation**

- 6) In case of setup failure, a message in red font will display and indicate the cause (in this example, the *JLinkDevices.xml* is not found due to a wrong installation path). Users need to re-install, and select the correct installation path (i.e., J-Link installation path).

Figure 17. AT32 package setup – Installation failure



## 3 High-Speed Sampling (HSS)

### 3.1 HSS mode

Load the “xxx.axf” file generated by MDK or “xxx.out” file generated by IAR to the J-Scope software.

Hardware connection: Use the standard download interface (VCC, GND, SWDIO, SWCLK and NRST) or 3-wire JLINK-OB (GND, SWDIO, SWCLK) for connection.

Advantages: It can be connected to the target board while the target is running, without additional resources, and users do not need to write the target board code.

Disadvantages: Compared with RTT mode, it has a lower sampling rate (basically fixed to 1 KHz), which is only applicable to variables with a change speed lower than 1 KHz.

### 3.2 Application method

This example uses MDK5 and AT32F403A for demonstration.

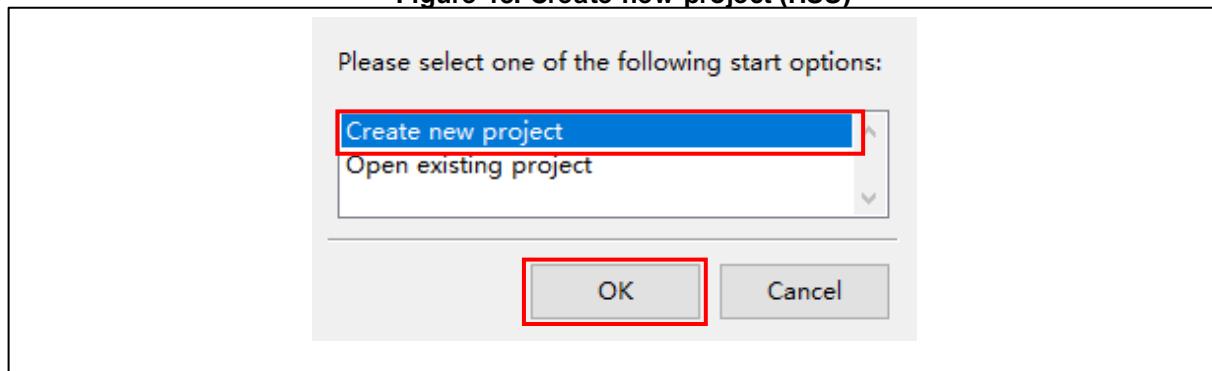
#### 3.2.1 Generate executable file

Open MDK project; compile and download program, and then generate an executable HSS.axf file.

#### 3.2.2 Create new project

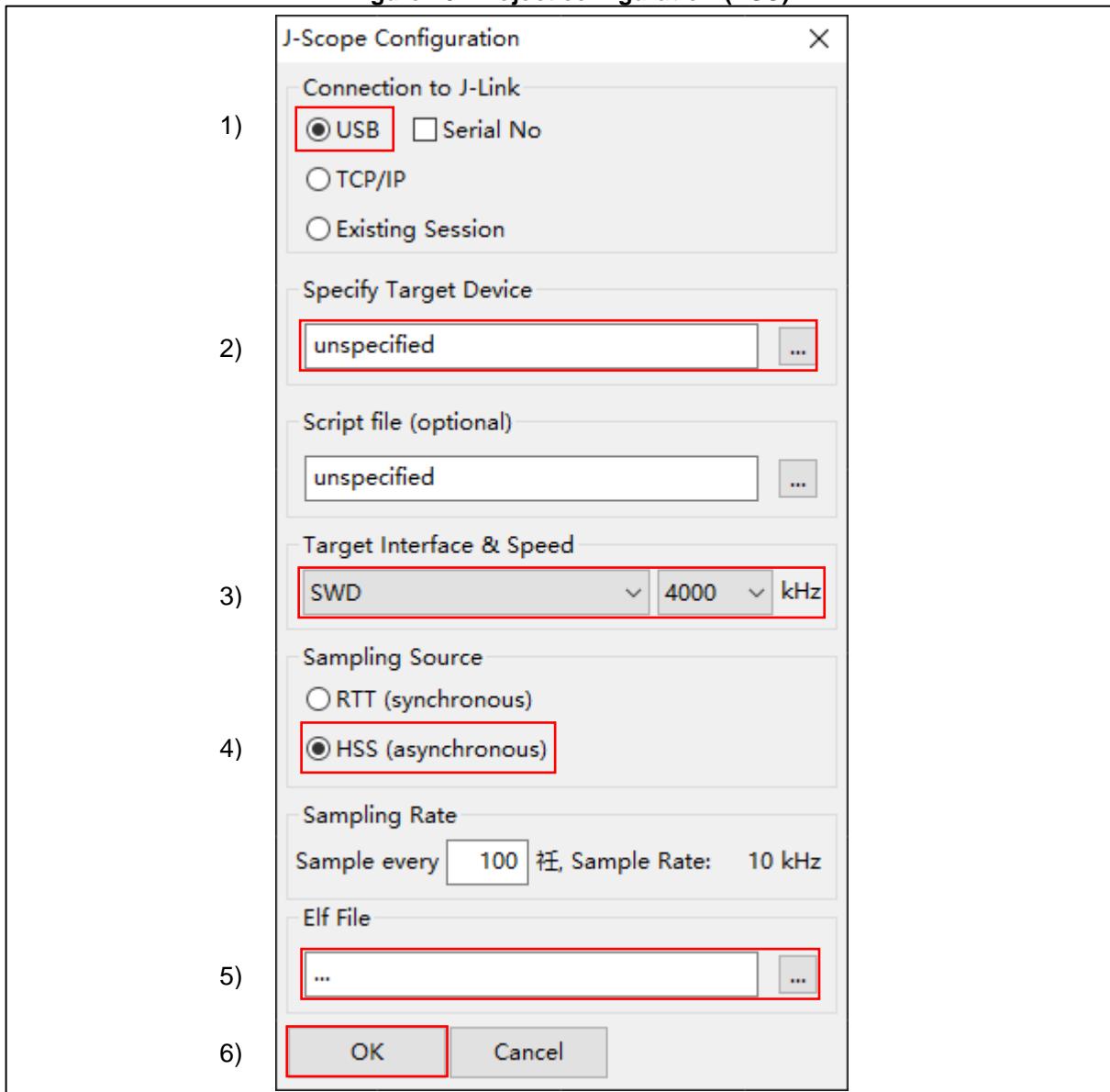
Open J-Scope, and create a new project.

Figure 18. Create new project (HSS)



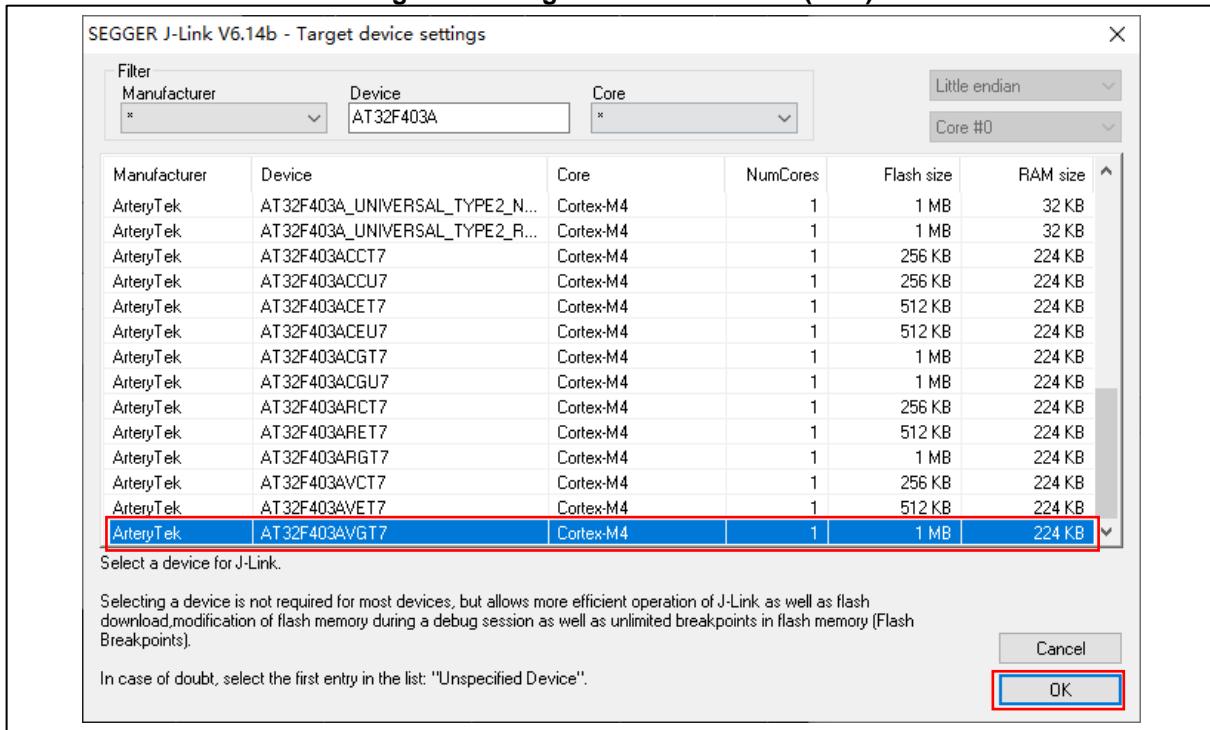
### 3.2.3 Configure project

Figure 19. Project configuration (HSS)



- 1) J-Link interface: Select J-Link USB interface;
- 2) Target device: Select AT32F403AVGT7;

Figure 20. Target device selection (HSS)

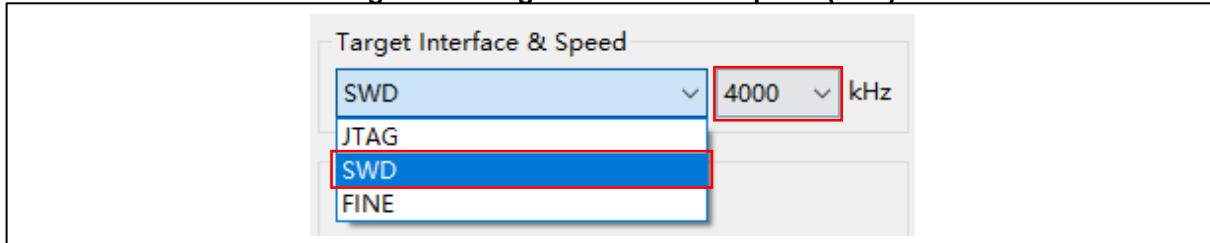


## 3) Target interface and speed:

Target interface: Select SWD or JTAG according to the application configuration. This example selects SWD.

J-Link speed: This example selects 4000 KHz.

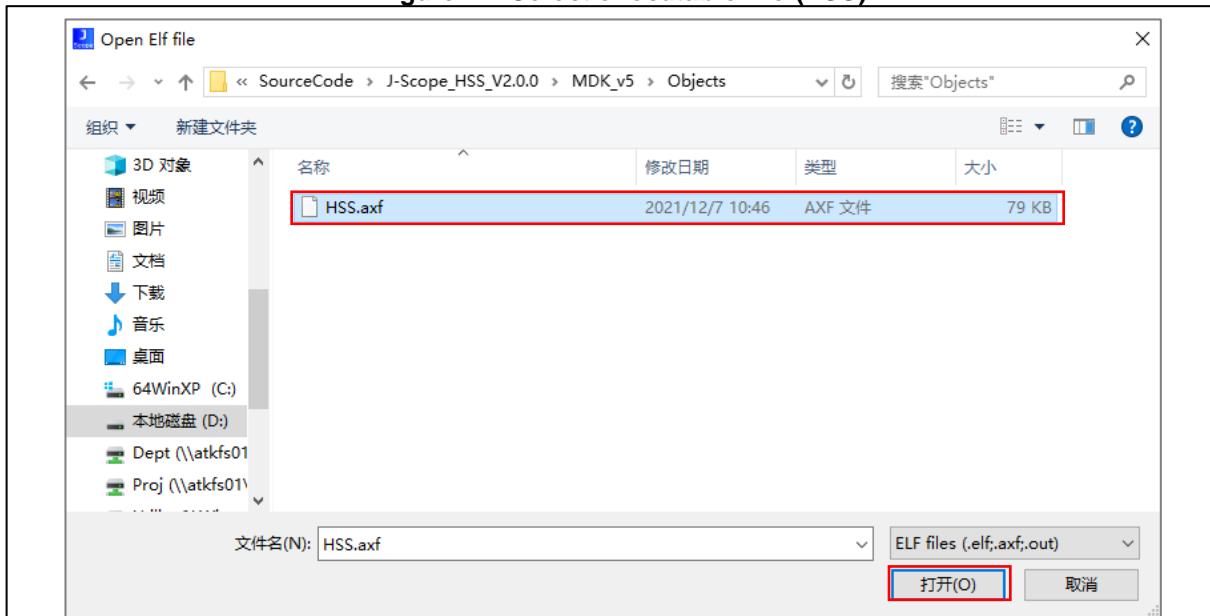
Figure 21. Target interface and speed (HSS)



## 4) Mode selection: Select HSS.

## 5) Executable file: Select the HSS.axf file in the path of MDK program.

Figure 22. Select executable file (HSS)

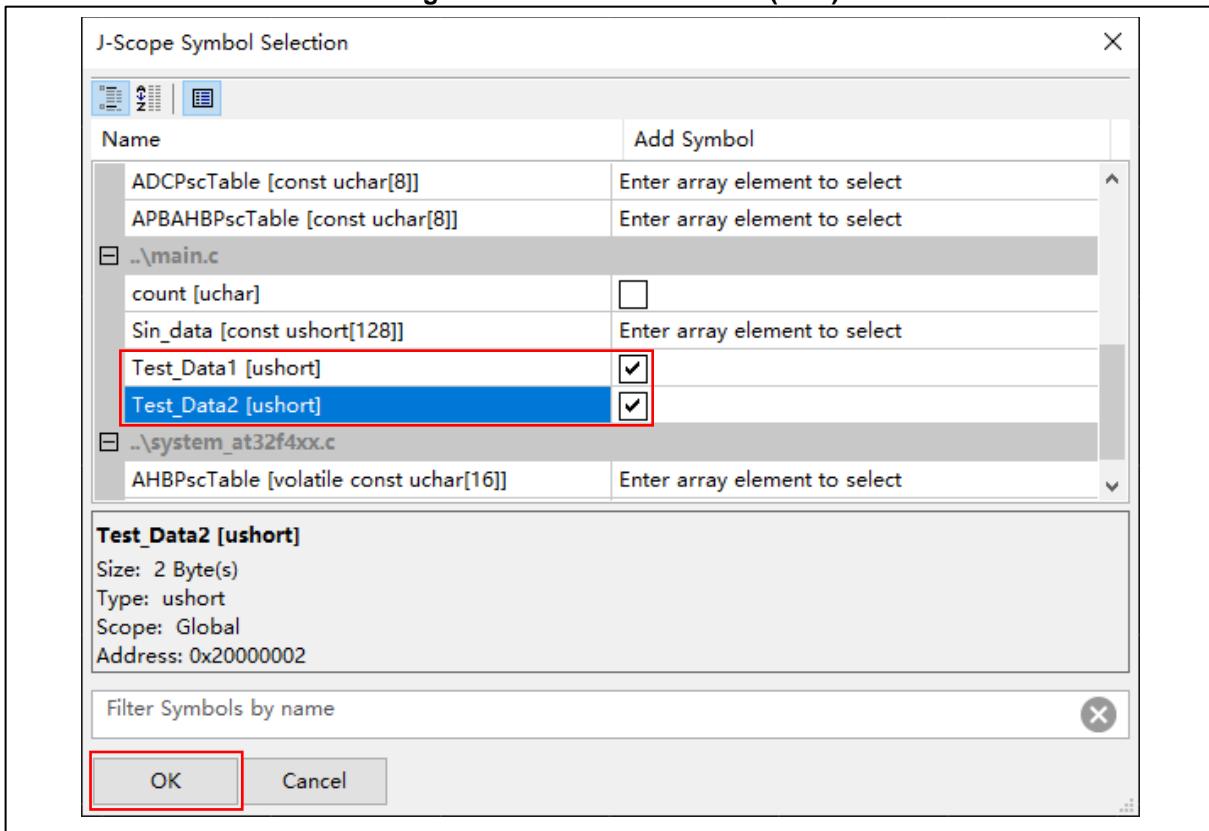


- 6) Configuration is finished, and click “OK”.

### 3.2.4 Select variables

- 1) Select and tick the desired variables;
- 2) Click “OK”;

Figure 23. Variable selection (HSS)



### 3.2.5 Start to run

- 1) Click the red dot, and data will be displayed;
- 2) A warning message pops up; click “OK”.

Figure 24. Start to run (HSS)

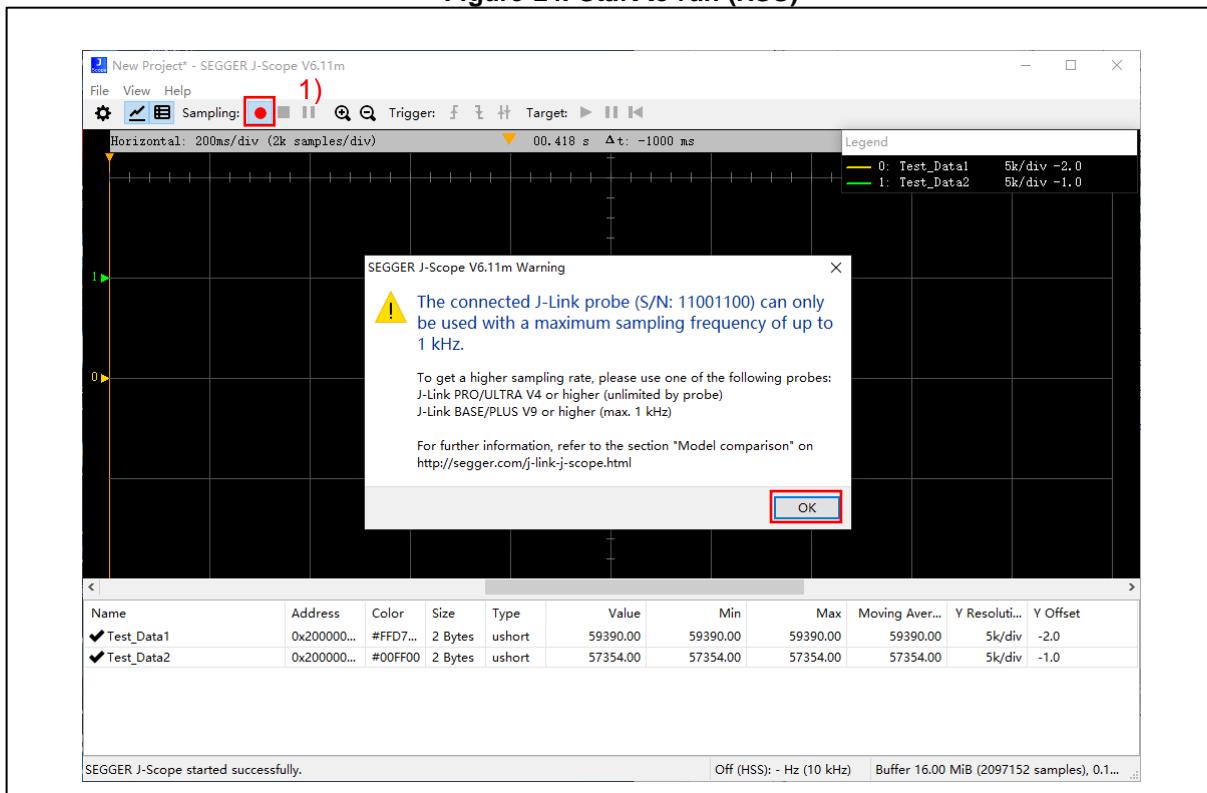
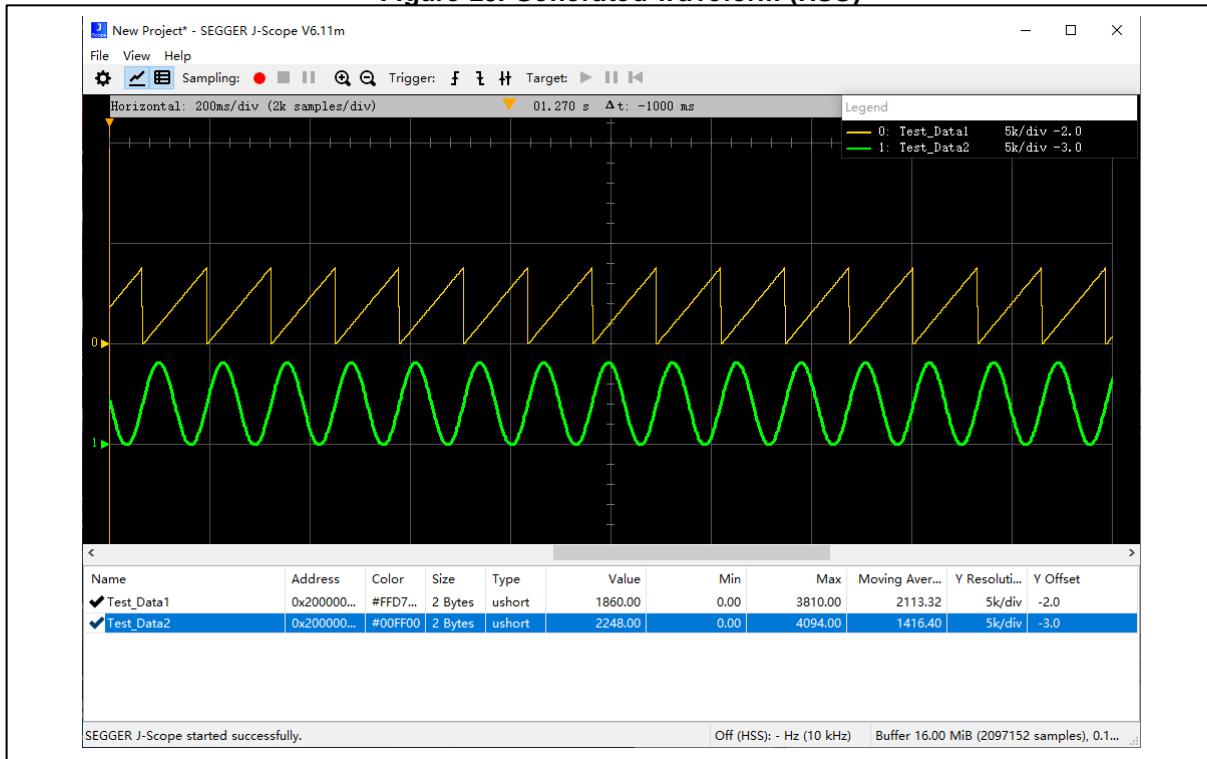


Figure 25. Generated waveform (HSS)



## 4 Real Time Transfer (RTT)

### 4.1 RTT mode

The RTT mode, similar to data upload over serial port, requires RTT component migration, uplink buffer configuration, and data transmission.

Hardware connection: Use the standard download interface (VCC, GND, SWDIO, SWCLK and NRST) or 3-wire JLINK-OB (GND, SWDIO, SWCLK) for connection.

Advantages:

- It has a higher sampling rate (up to 2 MB/s) than HSS mode; and support 1 MB/s sampling rate even if the target has a 512-byte buffer.
- Data acquisition is synchronized with the execution of the target board application because the application decides when to sample the data.
- Timestamp and other data can be added to the data sample.

Disadvantages:

- It requires migration of RTT components, which is more complex than HSS mode.

### 4.2 Application method

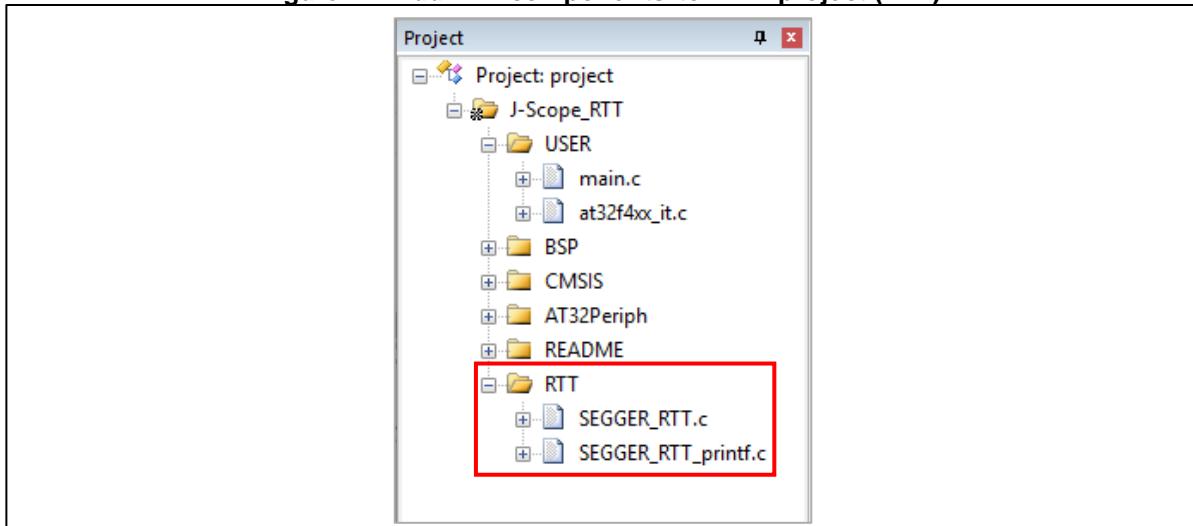
#### 4.2.1 Port RTT components

- 1) Copy the below four files to the MDK project path, and add to the MDK project.

Figure 26. RTT components (RTT)

SEGGER_RTT	2018/1/22 15:49	C 文件	34 KB
SEGGER_RTT	2018/1/22 15:49	H 文件	11 KB
SEGGER_RTT_Conf	2018/1/22 15:49	H 文件	4 KB
SEGGER_RTT_printf	2018/2/3 1:38	C 文件	17 KB

Figure 27. Add RTT components to MDK project (RTT)



- 2) Call the below function to configure the uplink buffer.

```
SEGGER_RTT_ConfigUpBuffer(1, "JScope_u4u2", buf, 2048, SEGGER_RTT_MODE_NO_BLOCK_SKIP);
```

- Parameter 1: buffer index—select 1
- Parameter 2: data format—fixed to “JScope\_xy”

Table 1. Data format

Type (x)	Data size (y)	Description
t	4	Each packet sent will be preceded by a timestamp, with 32-bit variables, in terms of $\mu$ s.
i	1, 2, 4	8/16/32-bit, with symbol variables
u	1, 2, 4	8/16/32-bit, without symbol variables

For example:

"JScope\_u4u2": Include 32-bit unsigned data and 16-bit unsigned data, and the data is arranged in the sequence of u4u2.

"JScope\_t4i4u2": Include 32-bit timestamp, 32-bit signed data and 16-bit unsigned data, and the data is arranged in the sequence of t4i4u2.

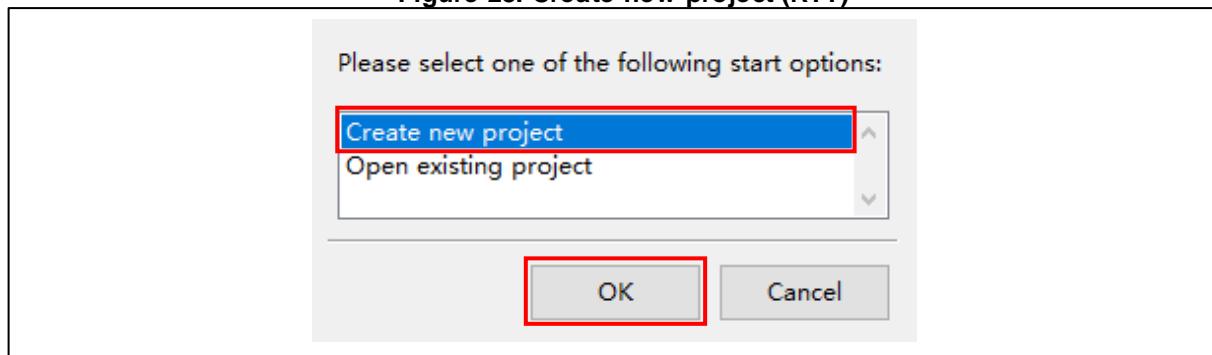
- Parameter 3: buffer selection
  - Parameter 4: buffer size
  - Parameter 5: mode—in RTT mode, the last parameter only supports SEGGER\_RTT\_MODE\_NO\_BLOCK\_SKIP and SEGGER\_RTT\_MODE\_BLOCK\_IF\_FIFO\_FULL. In this case, select SEGGER\_RTT\_MODE\_NO\_BLOCK\_SKIP.
- 3) Call the "SEGGER\_RTT\_Write" function to send data.

```
SEGGER_RTT_Write(1, &Test_Data1, 4);  
SEGGER_RTT_Write(1, &Test_Data2, 2);
```

4) Compile and download the application.

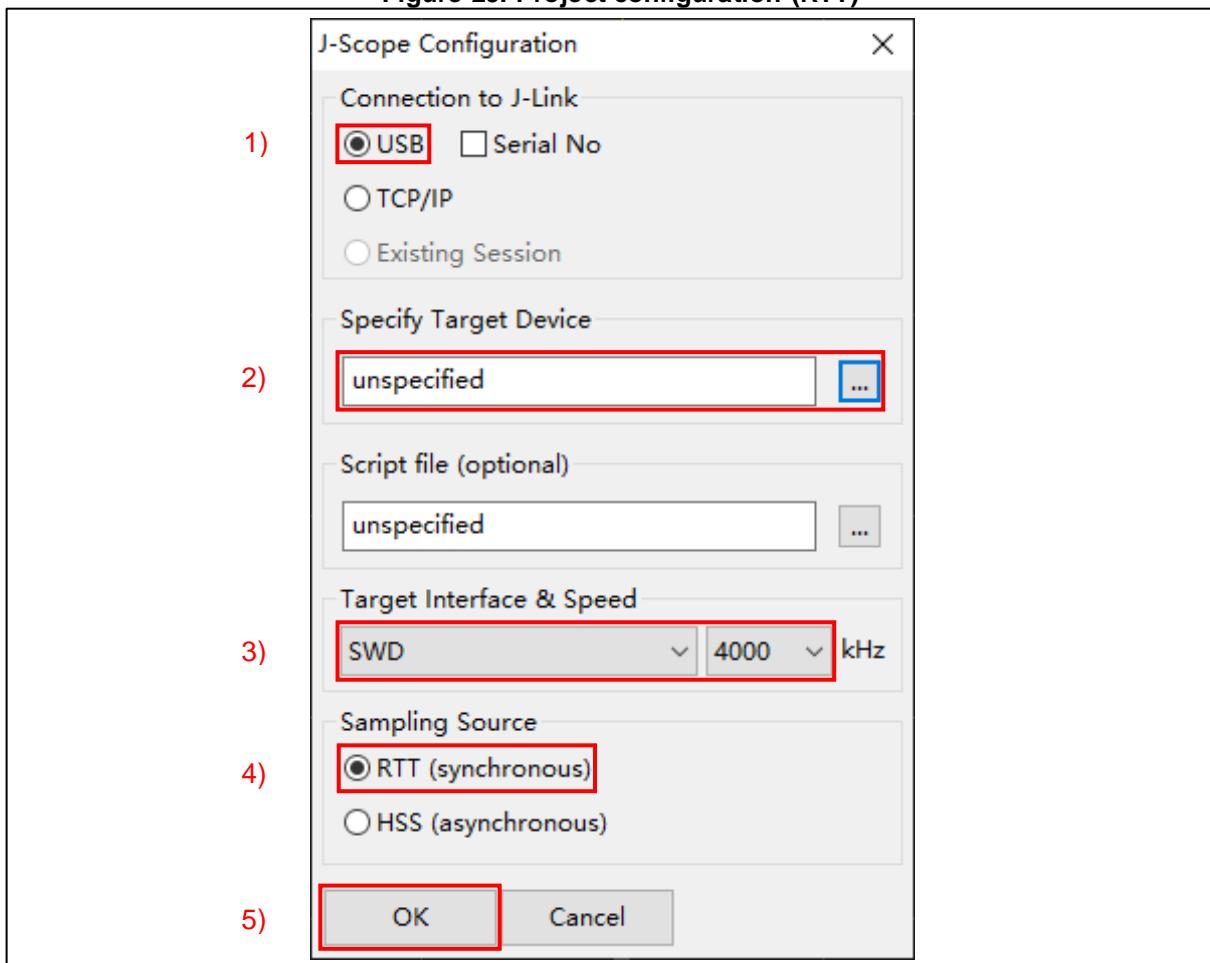
#### 4.2.2 Open J-Scope and create new project

Figure 28. Create new project (RTT)



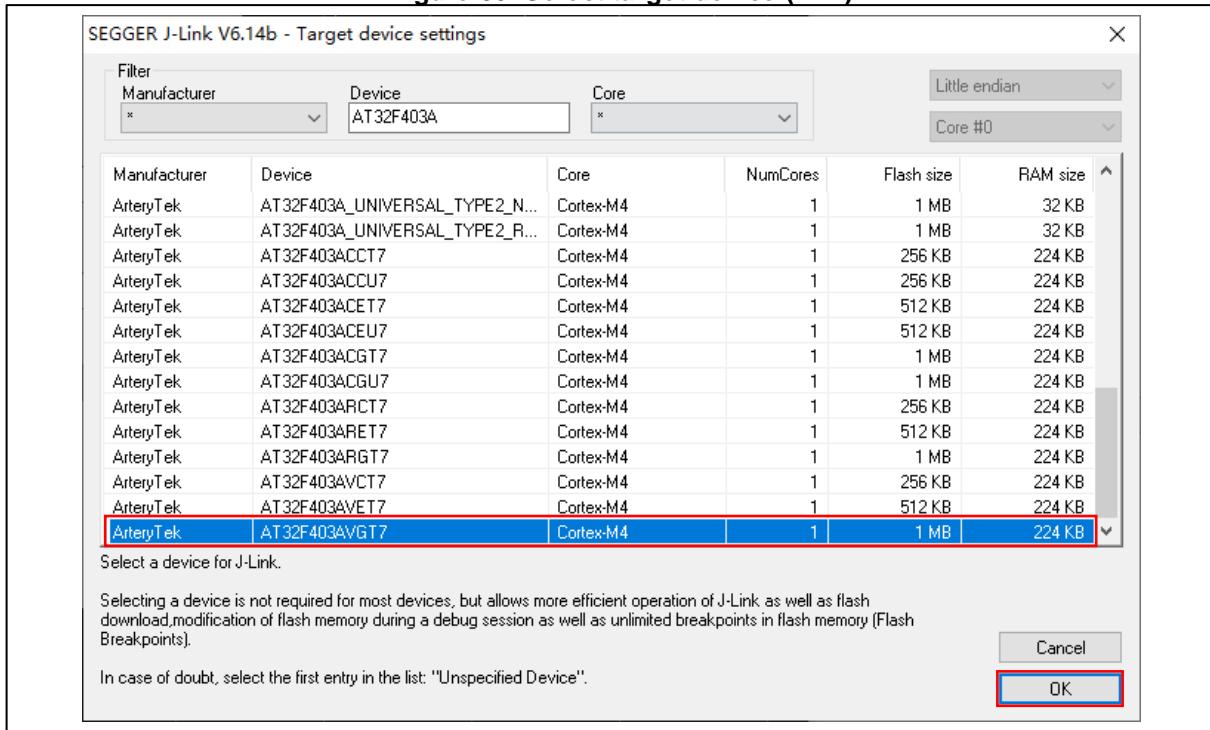
## 4.2.3 Configure project

Figure 29. Project configuration (RTT)



- 1) J-Link interface: Select J-Link USB interface;
- 2) Target device: Select AT32F403AVGT7;

Figure 30. Select target device (RTT)

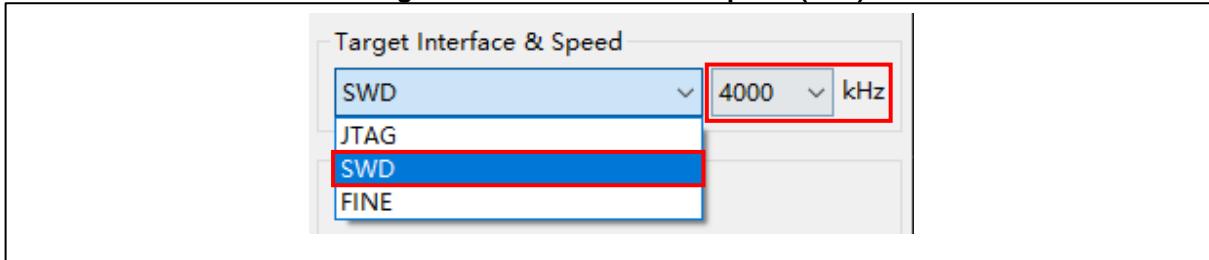


3) Target interface/speed:

Target interface: Select SWD or JTAG according to the application configuration. This example selects SWD.

J-Link speed: This example selects 4000 KHz.

Figure 31. Select interface/speed (RTT)



4) Mode selection: Select RTT;

5) Configuration is finished, and click "OK".

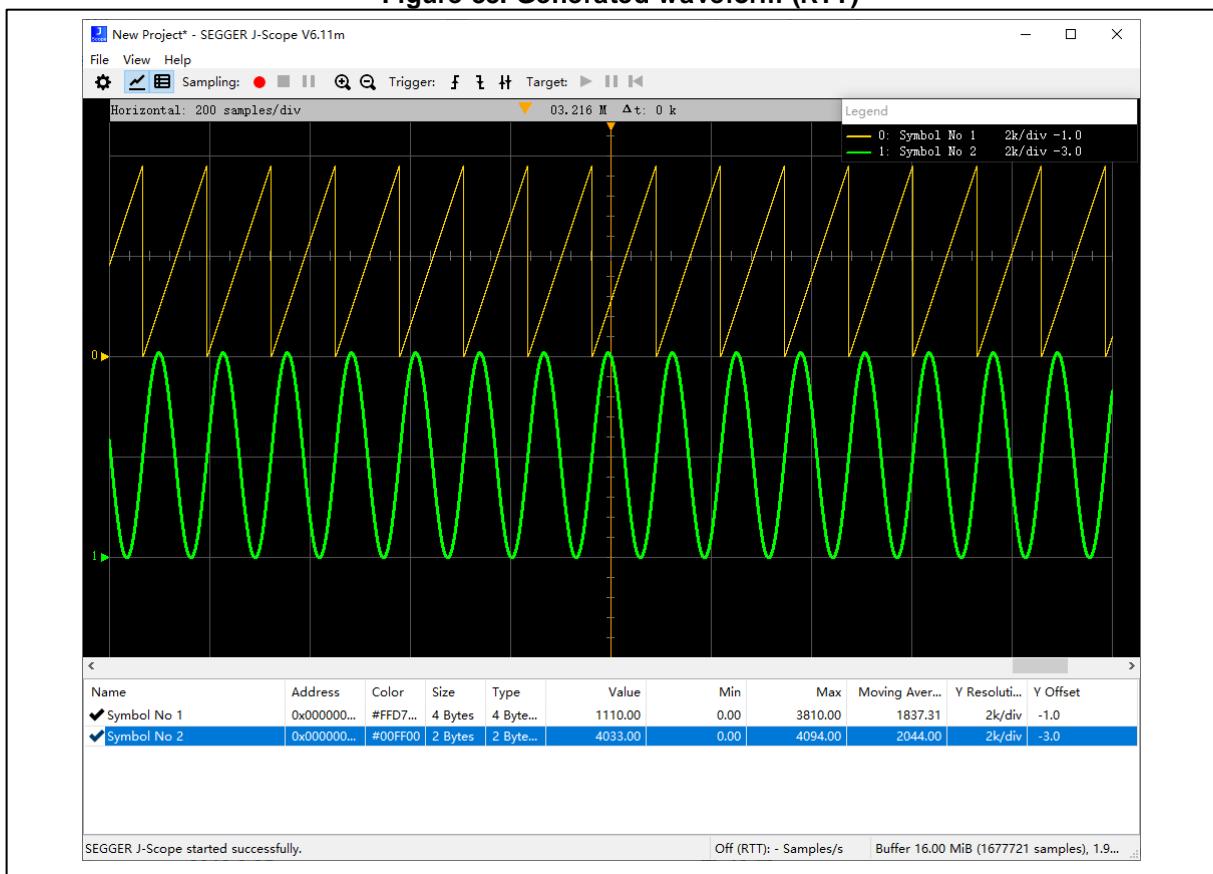
#### 4.2.4 Start to run

Click the red dot, and data will be displayed

Figure 32. Start to run (RTT)



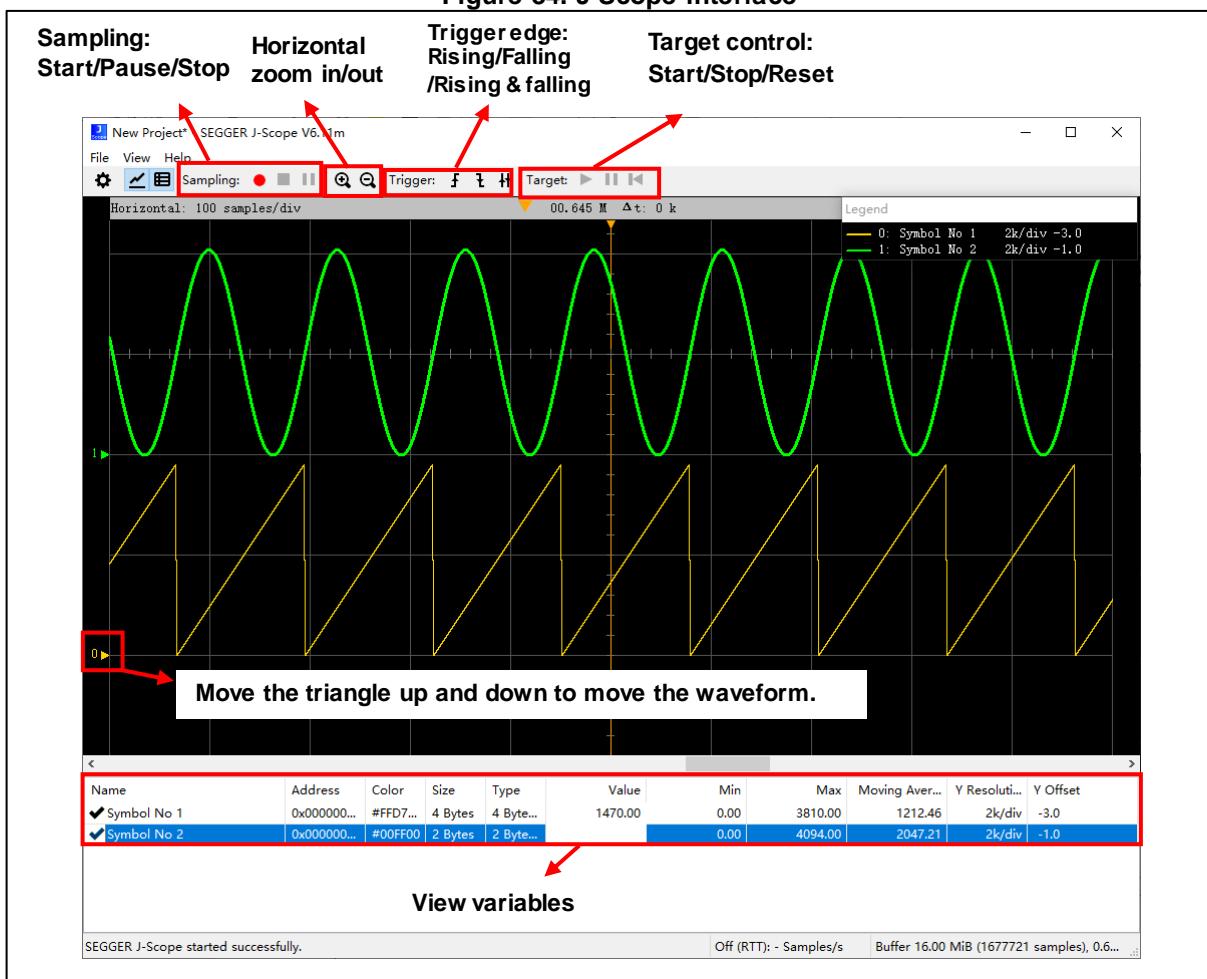
Figure 33. Generated waveform (RTT)



## 5 J-Scope software

### 5.1 Overview

Figure 34. J-Scope interface

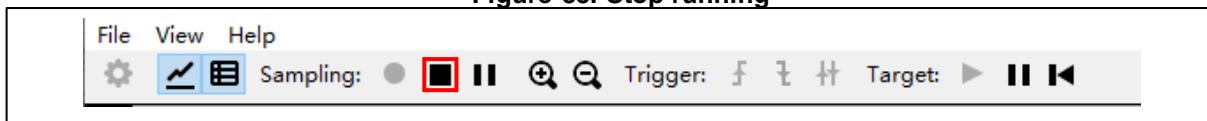


### 5.2 Export data

J-Scope can export data in CSV format or RAW format.

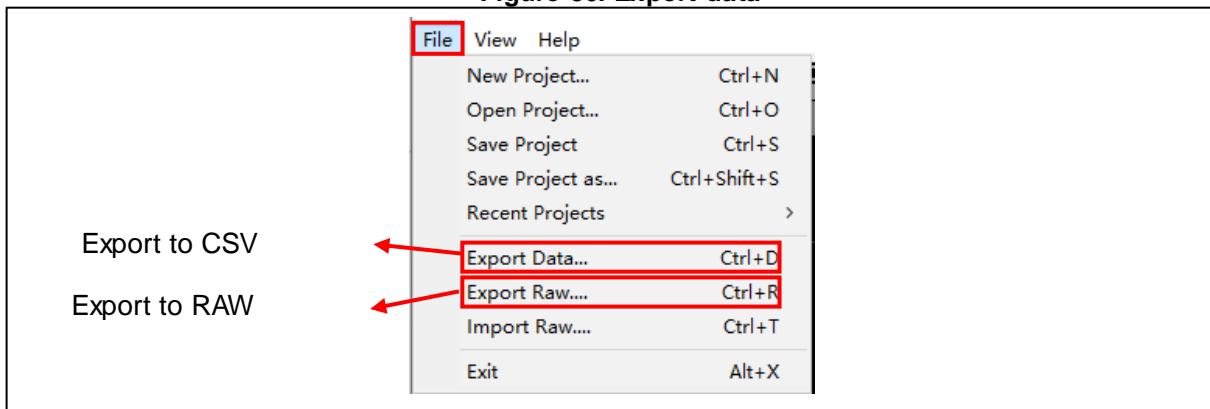
- 1) Stop running first if data sampling is in progress.

Figure 35. Stop running



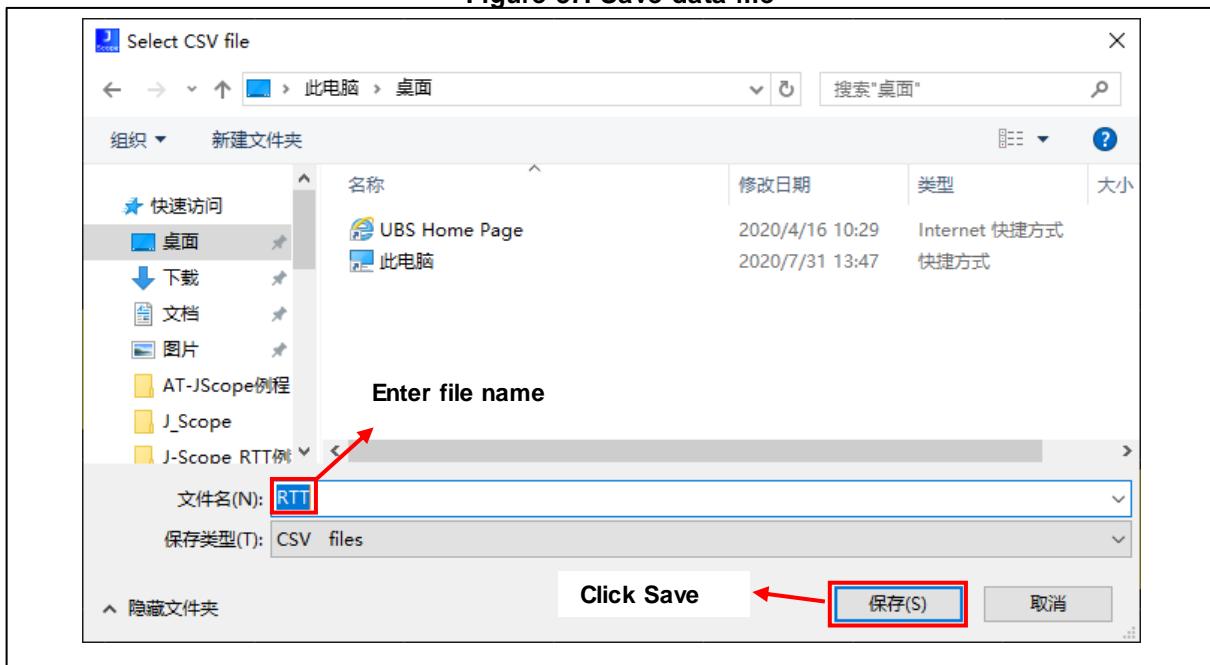
- 2) Click File->Export Data.

Figure 36. Export data



- 3) Enter the file name-> click “Save”.

Figure 37. Save data file



- 4) Open RTT.CSV to view the stored data, as shown in Figure 38 below.

Figure 38. Open data file

Timestamp	Symbol No	1
100	0	
200	30	
300	60	
400	90	
500	120	
600	150	
700	180	
800	210	
900	240	
1000	270	
1100	300	
1200	330	

## 5.3 Shortcuts

Figure 39. Shortcuts

Function	GUI Input	Shortcut
Graph Area Settings		
Zoom in (X-Axis)	Toolbar	Ctrl + Wheel up
Zoom out (X-Axis)	Toolbar	Ctrl + Wheel down
Set Zoom target	Drag ZTI	N/A
Change X-Axis scope	Move Scrollbar / Drag Graph Area	Wheel up / down
Symbol Settings (Apply to the symbol currently selected)		
Add Symbol	Symbol Context menu	N/A
Remove Symbol	Symbol Context menu	Delete
Show / Hide toggle	Symbol Context menu	Enter, Space
Zoom in (Y-Axis)	Symbol Context menu	+
Zoom out (Y-Axis)	Symbol Context menu	-
Change draw style	Symbol Context menu	N/A
(Hexa-)Decimal toggle	Symbol Context menu	N/A
Change color	Symbol Context menu	N/A
Y-Offset up	Drag Base Line Indicator	Ctrl + +
Y-Offset down	Drag Base Line Indicator	Ctrl + -
Sampling Controls		
Start Sampling	Toolbar	N/A
Stop Sampling	Toolbar	N/A
Pause Sampling	Toolbar	N/A
Start Target	Toolbar	N/A
Halt Target	Toolbar	N/A
Reset Target	Toolbar	N/A
General		
Exit J-Scope	File Menu	Alt + X
About Dialog	Help Menu	F1
Project Management		
Open Project	File Menu	Ctrl + O
New Project	File Menu	Ctrl + N
Save Project	File Menu	Ctrl + S
Save Project as	File Menu	Ctrl + Shift + S
Export CSV	File Menu	Ctrl + D
Export RAW	File Menu	Ctrl + R
Import RAW	File Menu	Ctrl + T

## 6 Demo program

Note: All projects are based on keil 5. For usage in other compiling environment, please refer to the corresponding environment (IAR6/7, keil 4/5) in AT32xxx\_Firmware\_Library\_V2.x.x\project\at\_start\_xxx\templates and complete proper modifications.

### 6.1 HSS mode

- 1) Unzip and open xx\AN0044\_Segger\_Jscope\_on\_AT32\_MCU\_2.0.0\SourceCode\J-Scope\_HSS\_V2.0.0;
- 2) Define two global variables (Test\_Data1 and Test\_Data2);
- 3) Create a J-Scope project; select sampling variables (Test\_Data1 and Test\_Data2) and then click Start to run.

Figure 40. J-Scope HSS

```

Project
  Project: project
    J-Scope_HSS
      user
      bsp
      cmsis
      firmware
      readme

main.c

1 /**
2  ****
3   * File : main.c
4   * Version: V1.0.0
5   * Date : 2020-08-05
6   * Brief : Main program body
7  ****
8 */
9 #include "at32f403a_407_board.h"
10 #include "at32f403a_407_clock.h"
11
12 uint16_t Test_Data1;
13 uint16_t Test_Data2;
14 const uint16_t Cos_data[128] = {
15   2047, 2147, 2248, 2347, 2446, 2544, 2641, 2737, 2830, 2922, 3012, 3099, 3184, 3266, 3346, 3422,
16   3494, 3564, 3629, 3691, 3749, 3803, 3852, 3897, 3938, 3974, 4006, 4033, 4055, 4072, 4094, 4092,
17   4094, 4092, 4084, 4072, 4055, 4033, 4006, 3974, 3938, 3897, 3852, 3803, 3749, 3691, 3629, 3564,
18   3494, 3422, 3346, 3266, 3184, 3099, 3012, 2922, 2830, 2737, 2641, 2544, 2446, 2347, 2248, 2147,
19   2047, 1947, 1846, 1747, 1648, 1550, 1453, 1357, 1264, 1172, 1082, 995, 910, 828, 748, 672,
20   600, 530, 465, 403, 345, 291, 242, 197, 156, 120, 88, 61, 39, 22, 10, 2,
21   0, 2, 10, 22, 39, 61, 88, 120, 156, 197, 242, 291, 345, 403, 465, 530,
22   600, 672, 748, 828, 910, 995, 1082, 1172, 1264, 1357, 1453, 1550, 1648, 1747, 1846, 1947,
23 };
24 uint8_t count;
25
26 int main()
27 {
28   at32_board_init();
29
30   while(1)
31   {
32     Test_Data1 = (count%128)*30;           /*锯齿波*/
33     Test_Data2 = Cos_data[count%128];       /*余弦波*/
34     count++;
35     delay_ms(1);
36   }
37 }
38

```

### 6.2 RTT mode

- 1) Unzip and open xx\AN0044\_Segger\_Jscope\_on\_AT32\_MCU\SourceCode\ J-Scope\_RTT\_V1.x.x;
- 2) Port RTT components;
- 3) The *main.c* includes the SEGGER\_RTT.h file;
- 4) Define two global variables (Test\_Data1 and Test\_Data2);
- 5) Configure the uplink buffer.

```
SEGGER_RTT_ConfigUpBuffer(1, "JScope_u4u2", buf, 2048, SEGGER_RTT_MODE_NO_BLOCK_SKIP);
```

- 6) Export data.

```
SEGGER_RTT_Write(1, &Test_Data1, 4);
SEGGER_RTT_Write(1, &Test_Data2, 2);
```

- 7) Create a J-Scope RTT project, and then click Start to run and generate a waveform.

Figure 41. J-Scope RTT

The screenshot shows the Segger J-Scope software interface. On the left is a project tree titled 'Project: project' containing 'J-Scope\_HSS' which includes 'user', 'bsp', 'cmsis', 'firmware', 'RTT', and 'readme'. The main window displays the 'main.c' file with the following code:

```
1 /**
2  * File : main.c
3  * Version : V1.0.0
4  * Date : 2020-08-05
5  * Brief : Main program body
6  */
7 ****
8 */
9 #include "at32f403a_407_board.h"
10 #include "at32f403a_407_clock.h"
11 #include "SEGGER_RTT.h"
12
13 uint16_t buf[2048];
14 uint32_t Test_Data1;
15 uint16_t Test_Data2;
16 const uint16_t Cos_data[128] = {
17     4094, 4092, 4084, 4072, 4055, 4033, 4006, 3974, 3938, 3897, 3852, 3803, 3749, 3691, 3629, 3564,
18     3494, 3422, 3346, 3266, 3184, 3099, 3012, 2922, 2830, 2737, 2641, 2544, 2446, 2347, 2248, 2147,
19     2047, 1947, 1846, 1747, 1648, 1550, 1453, 1357, 1264, 1172, 1082, 995, 910, 828, 748, 672,
20     600, 530, 465, 403, 345, 291, 242, 197, 156, 120, 88, 61, 39, 22, 10, 2,
21     0, 2, 10, 22, 39, 61, 88, 120, 156, 197, 242, 291, 345, 403, 465, 530,
22     600, 672, 748, 828, 910, 995, 1082, 1172, 1264, 1357, 1453, 1550, 1648, 1747, 1846, 1947,
23     2047, 2147, 2248, 2347, 2446, 2544, 2641, 2737, 2830, 2922, 3012, 3099, 3184, 3266, 3346, 3422,
24     3494, 3564, 3629, 3691, 3749, 3803, 3852, 3897, 3938, 3974, 4006, 4033, 4055, 4072, 4084, 4092,
25 };
26 uint8_t count;
27
28 int main()
29 {
30     at32_board_init();
31
32     /* 配置通道1, 上行配置 */
33     SEGGER_RTT_ConfigUpBuffer(1, "JScope_u4u2", buf, 2048, SEGGER_RTT_MODE_NO_BLOCK_SKIP);
34     while(1)
35     {
36         Test_Data1 = (count%128)*30;           //缓齿波
37         Test_Data2 = Cos_data[count%128];      //余弦波
38         count++;
39
40         SEGGER_RTT_Write(1, &Test_Data1, 4);
41         SEGGER_RTT_Write(1, &Test_Data2, 2);
42
43         delay_us(100);
44     }
45 }
```

## 7 Revision history

Table 2. Document revision history

Date	Version	Revision note
2021.11.02	2.0.0	Initial release.

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